

Fig. 1

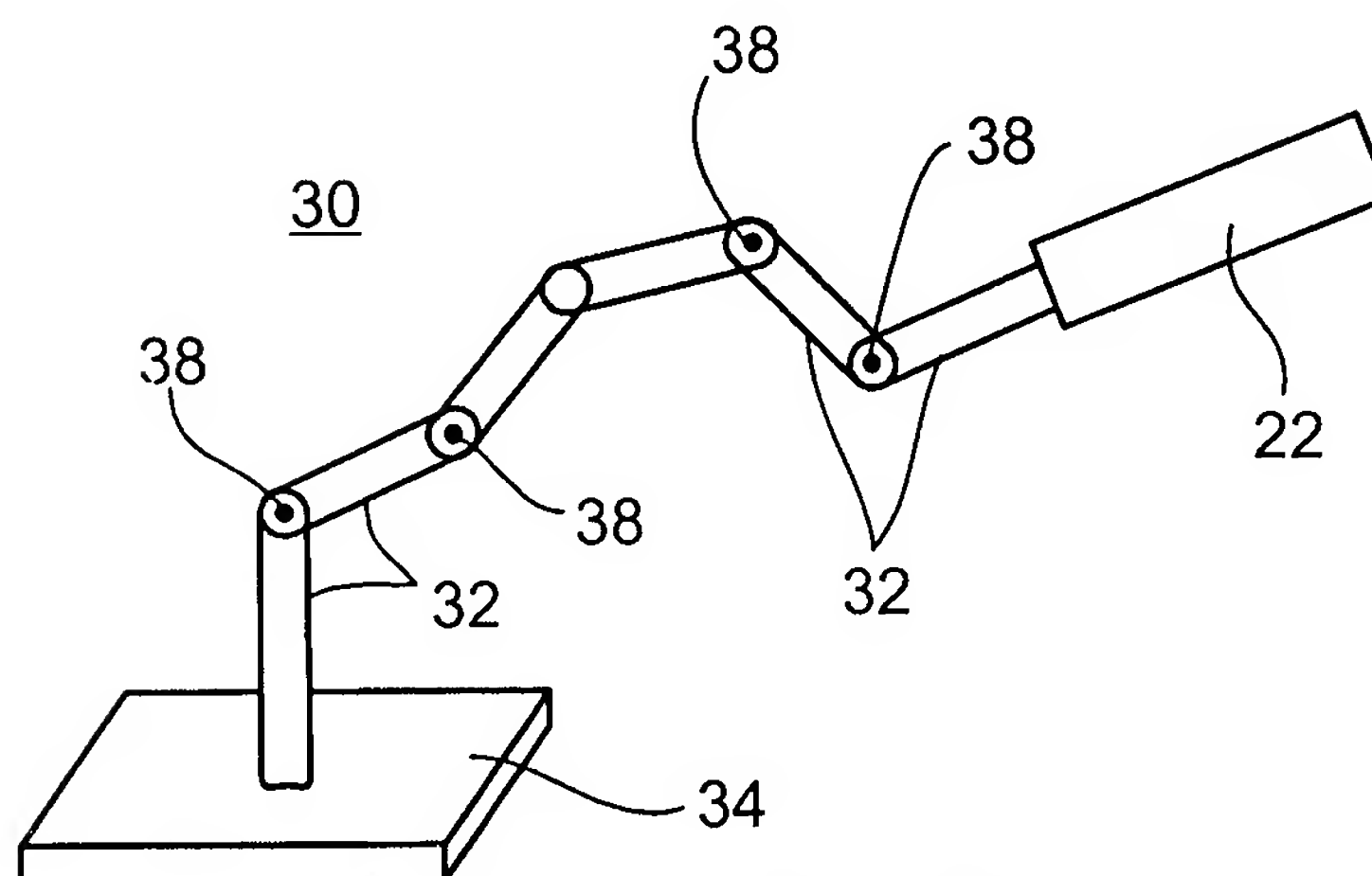


Fig. 2

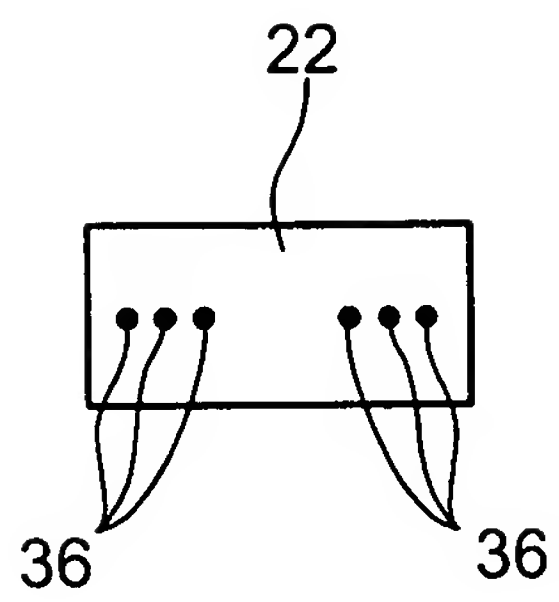


Fig. 3

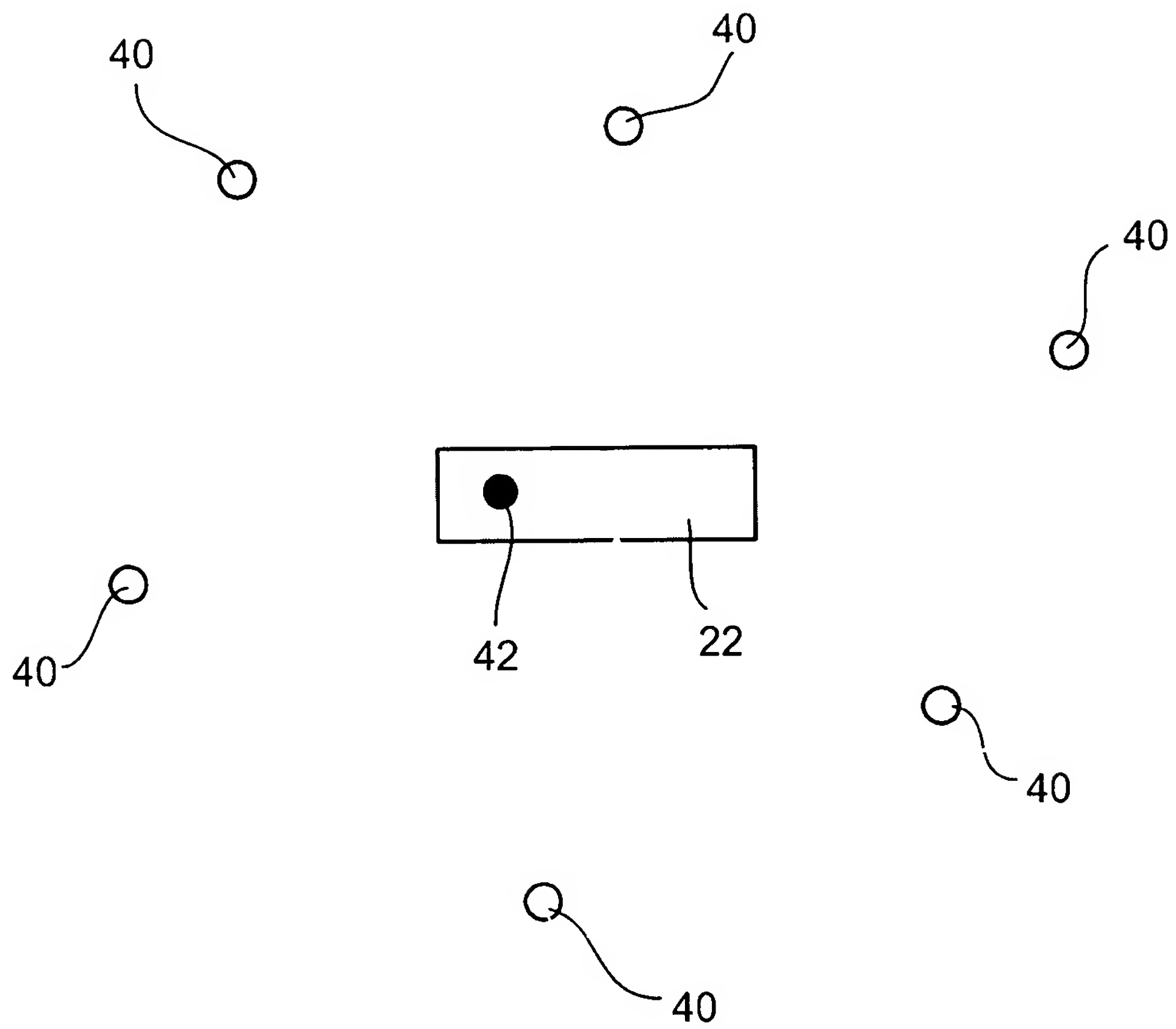


Fig. 4

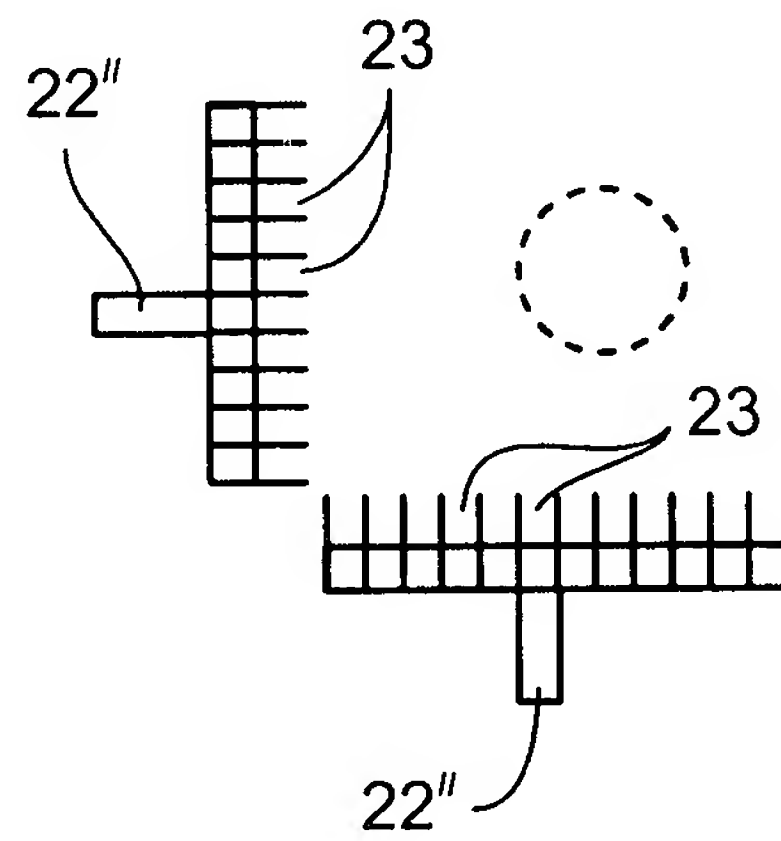
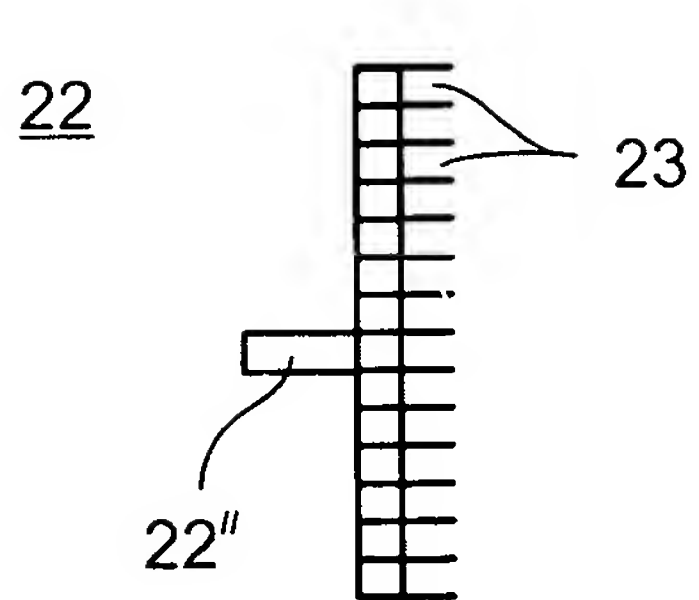
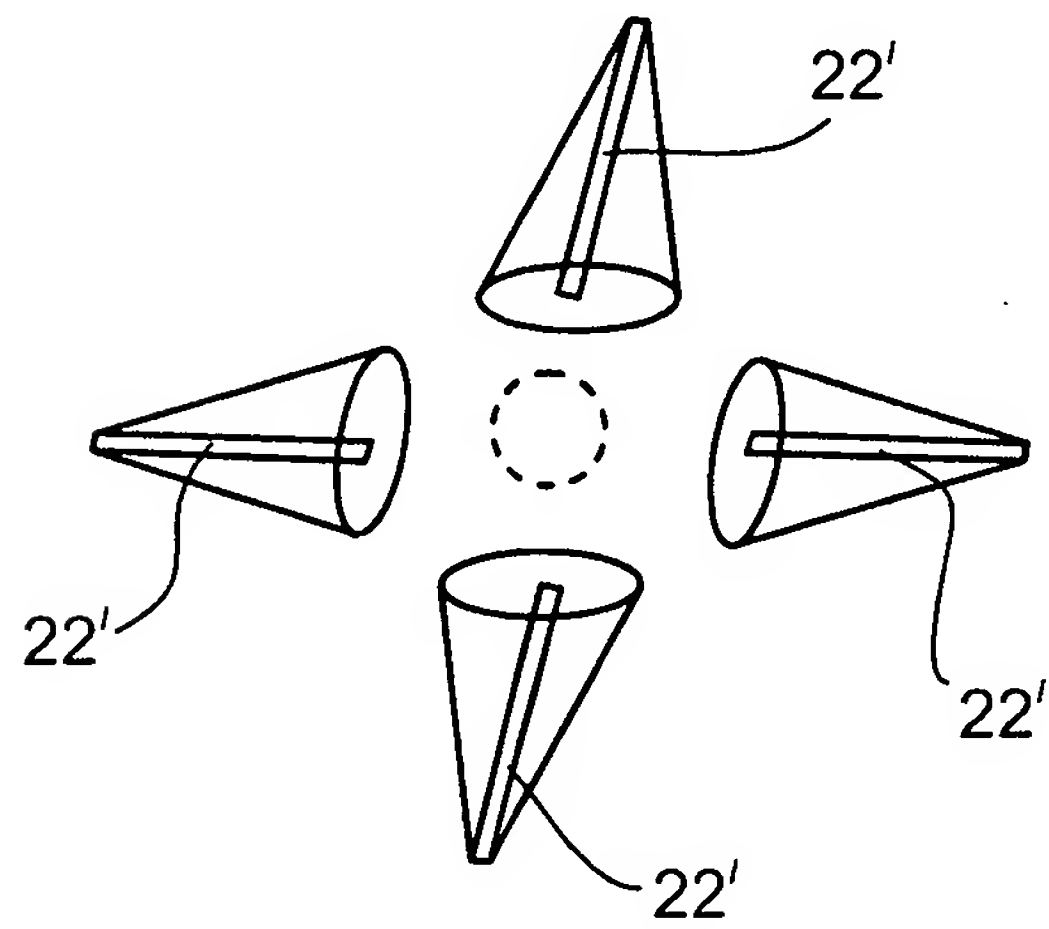
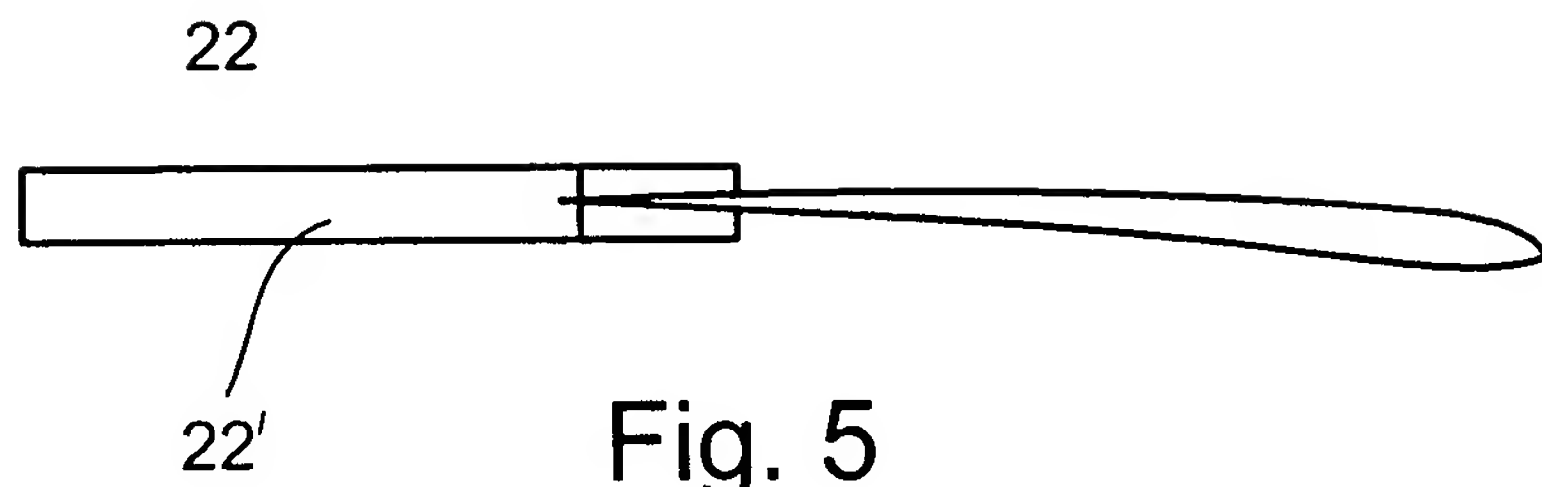


Fig. 7

Fig. 8

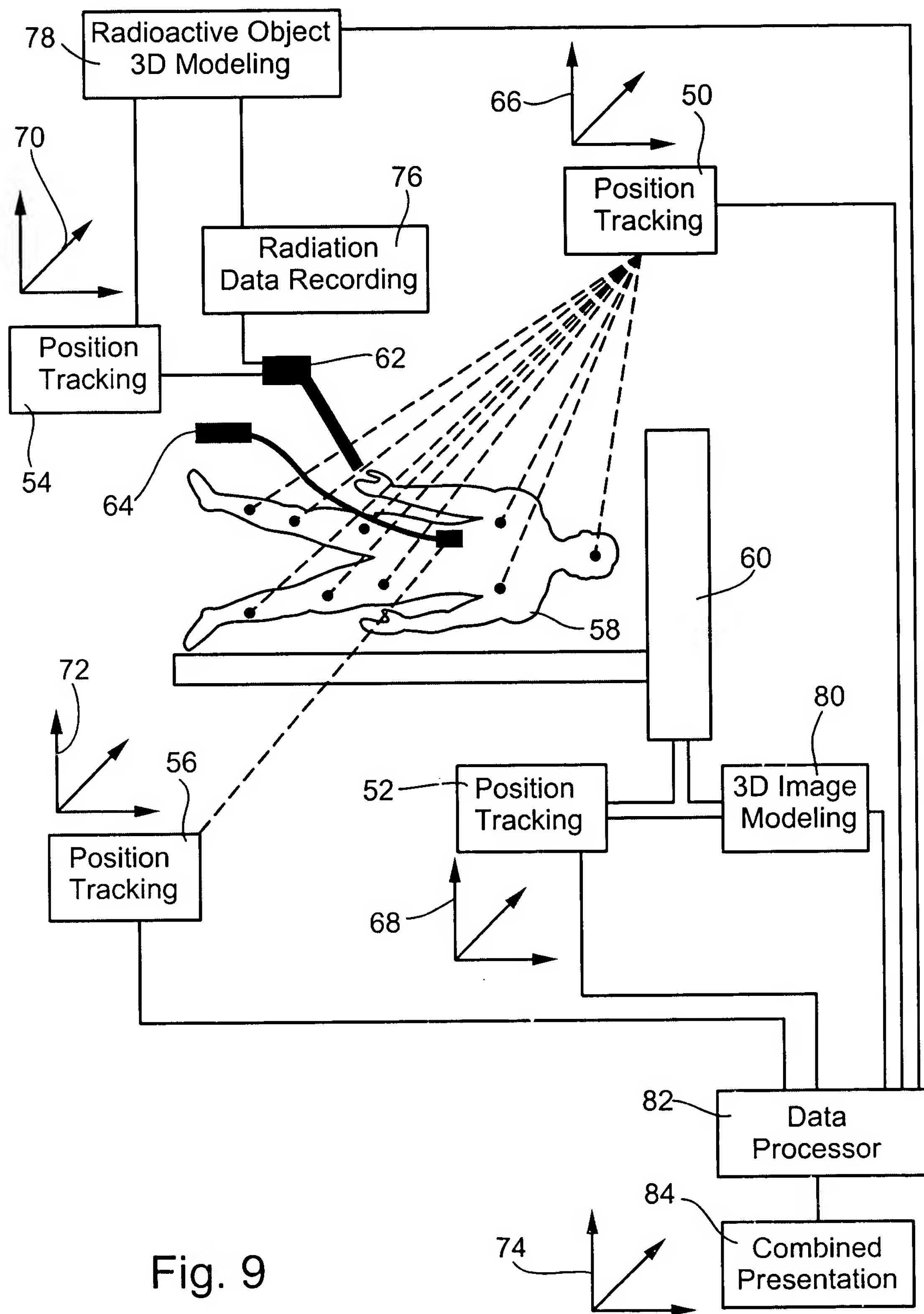


Fig. 9

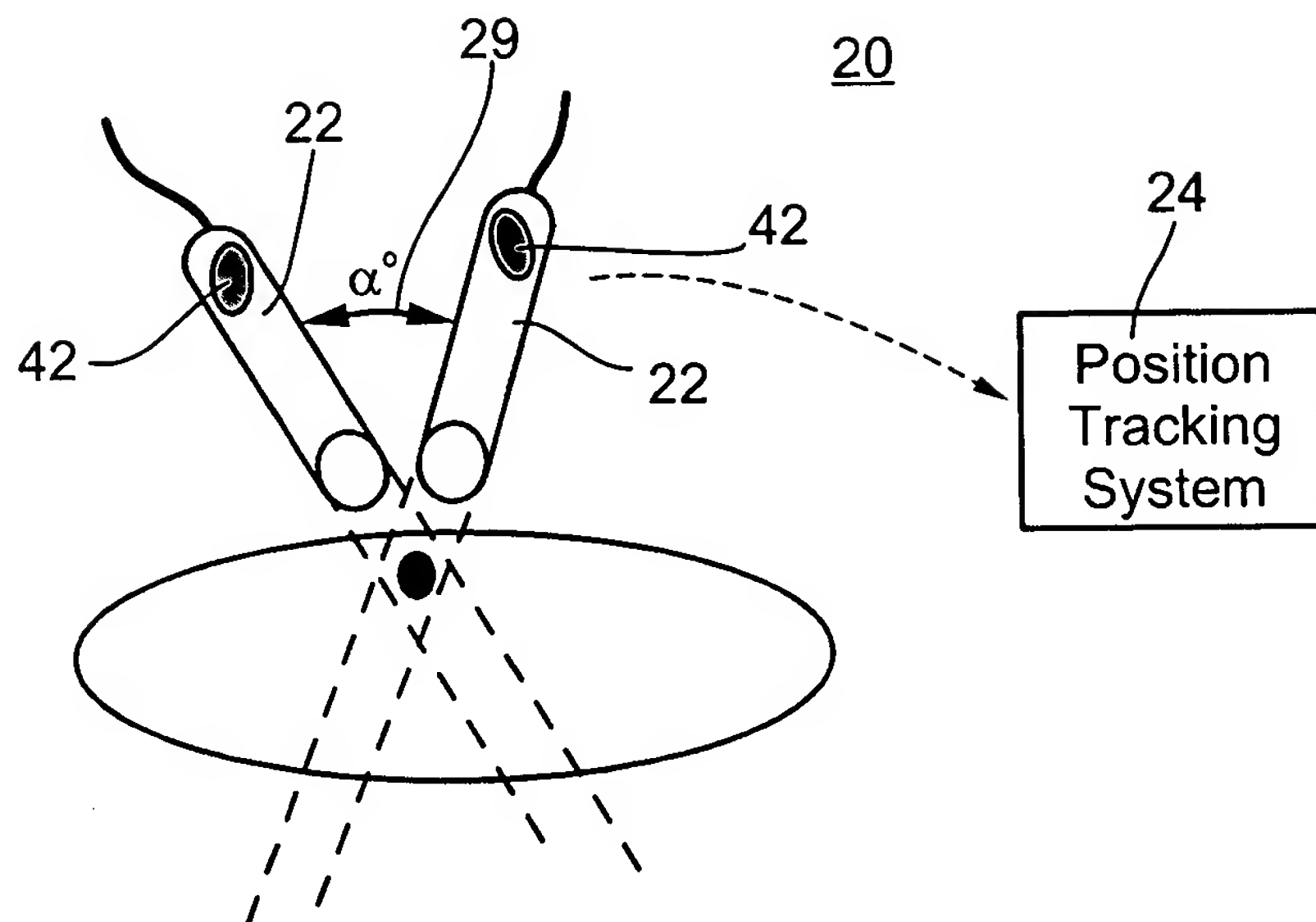


Fig. 10

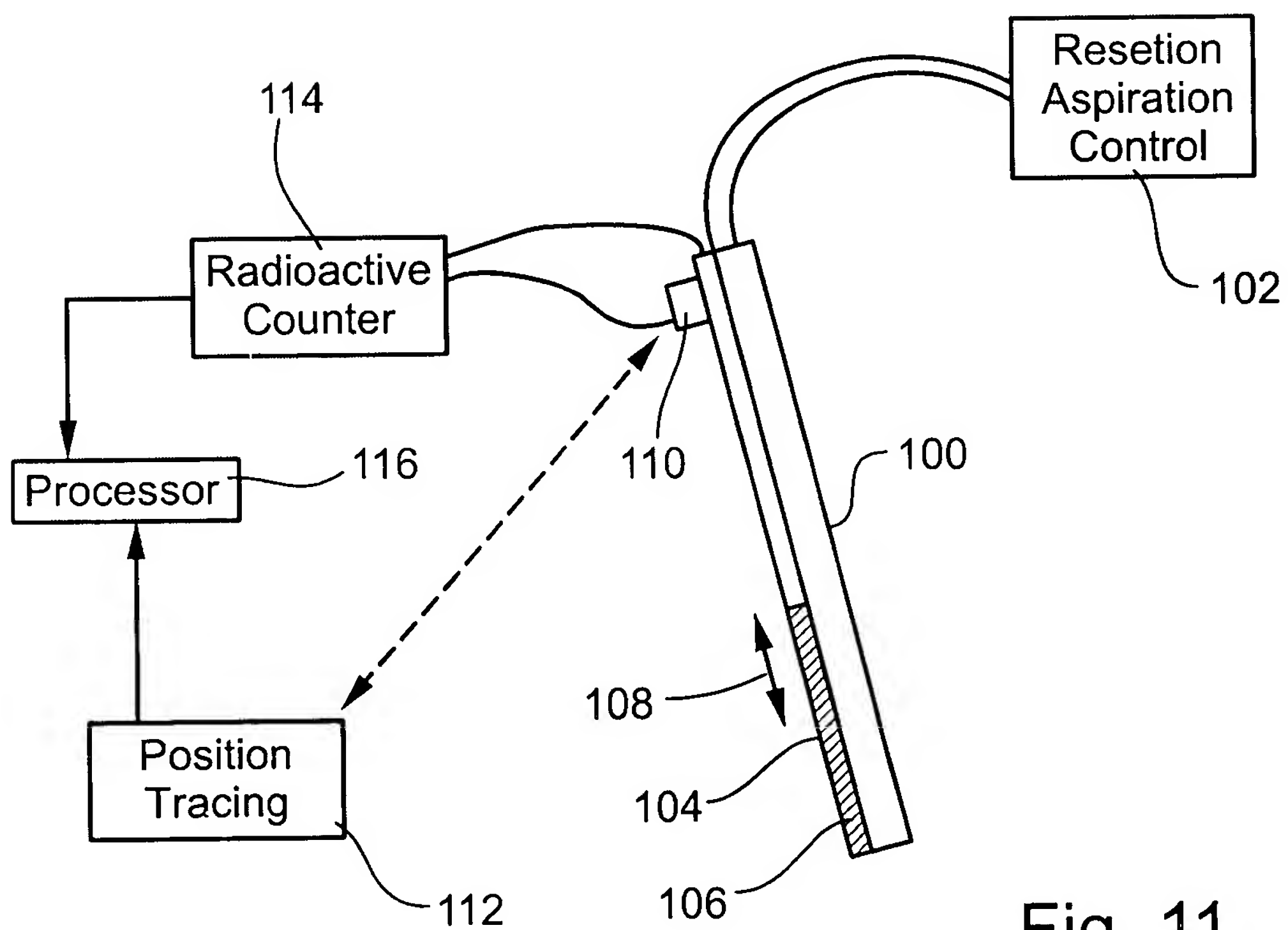


Fig. 11

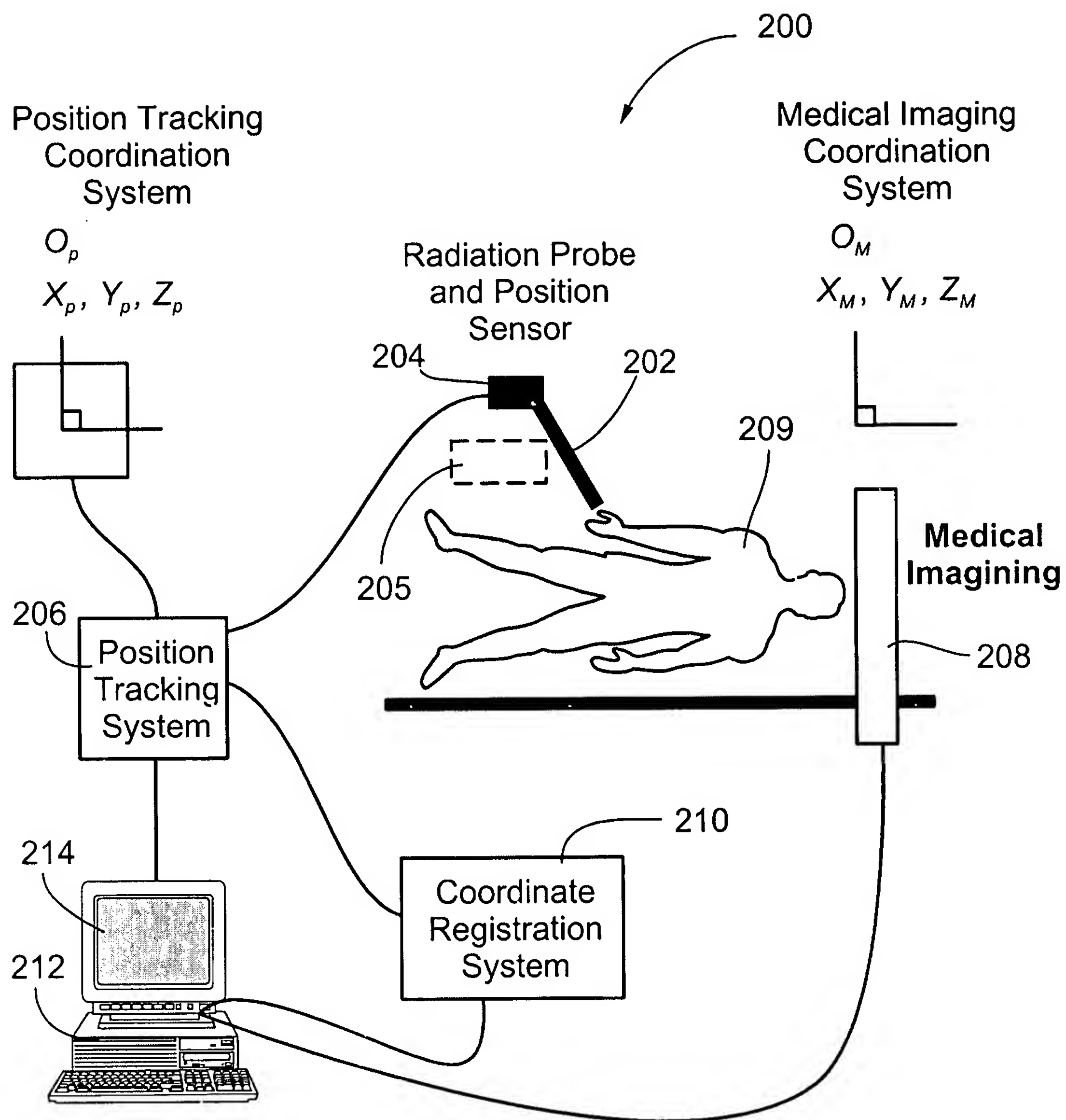


Fig. 12

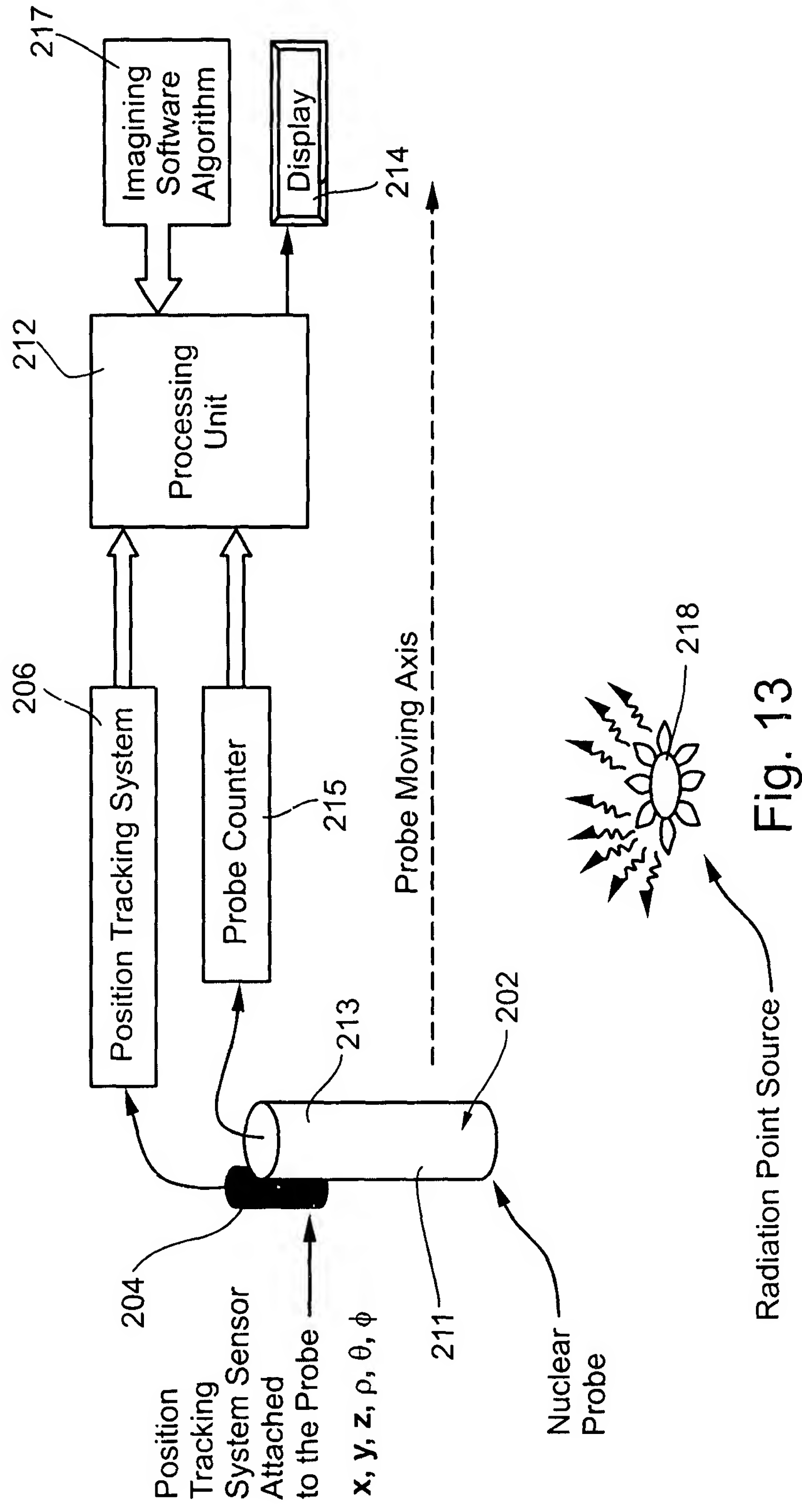


Fig. 13

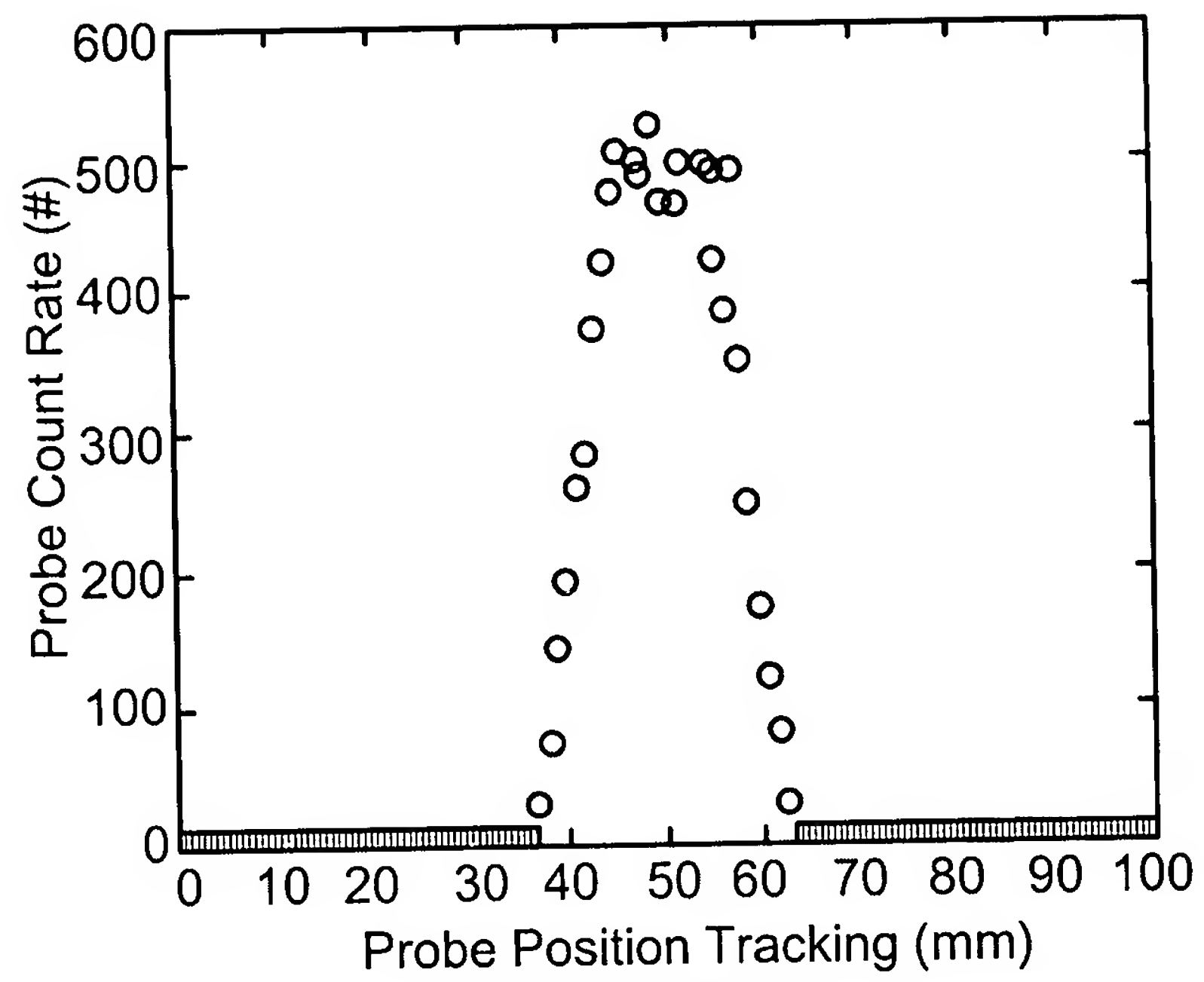


Fig. 14



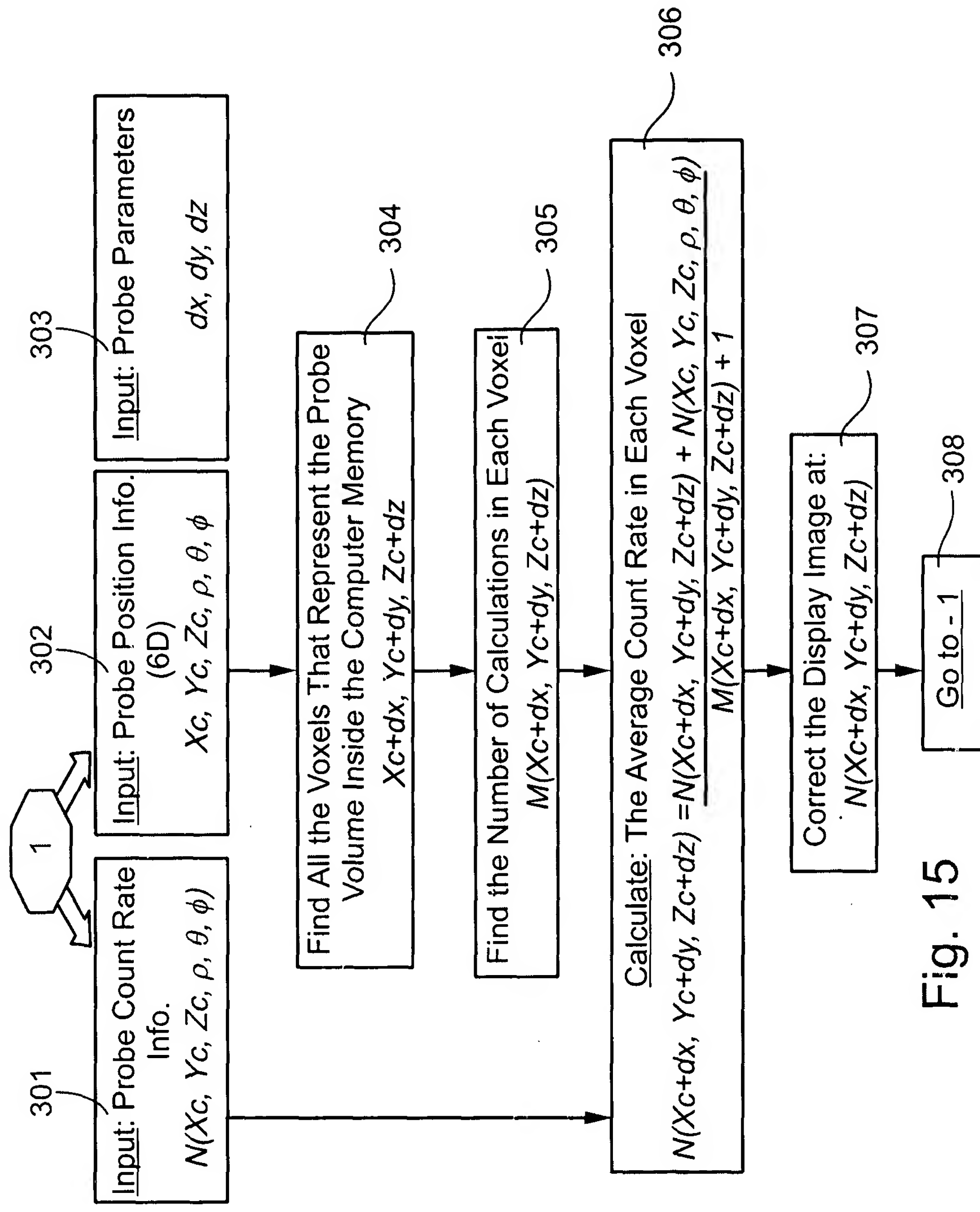


Fig. 15

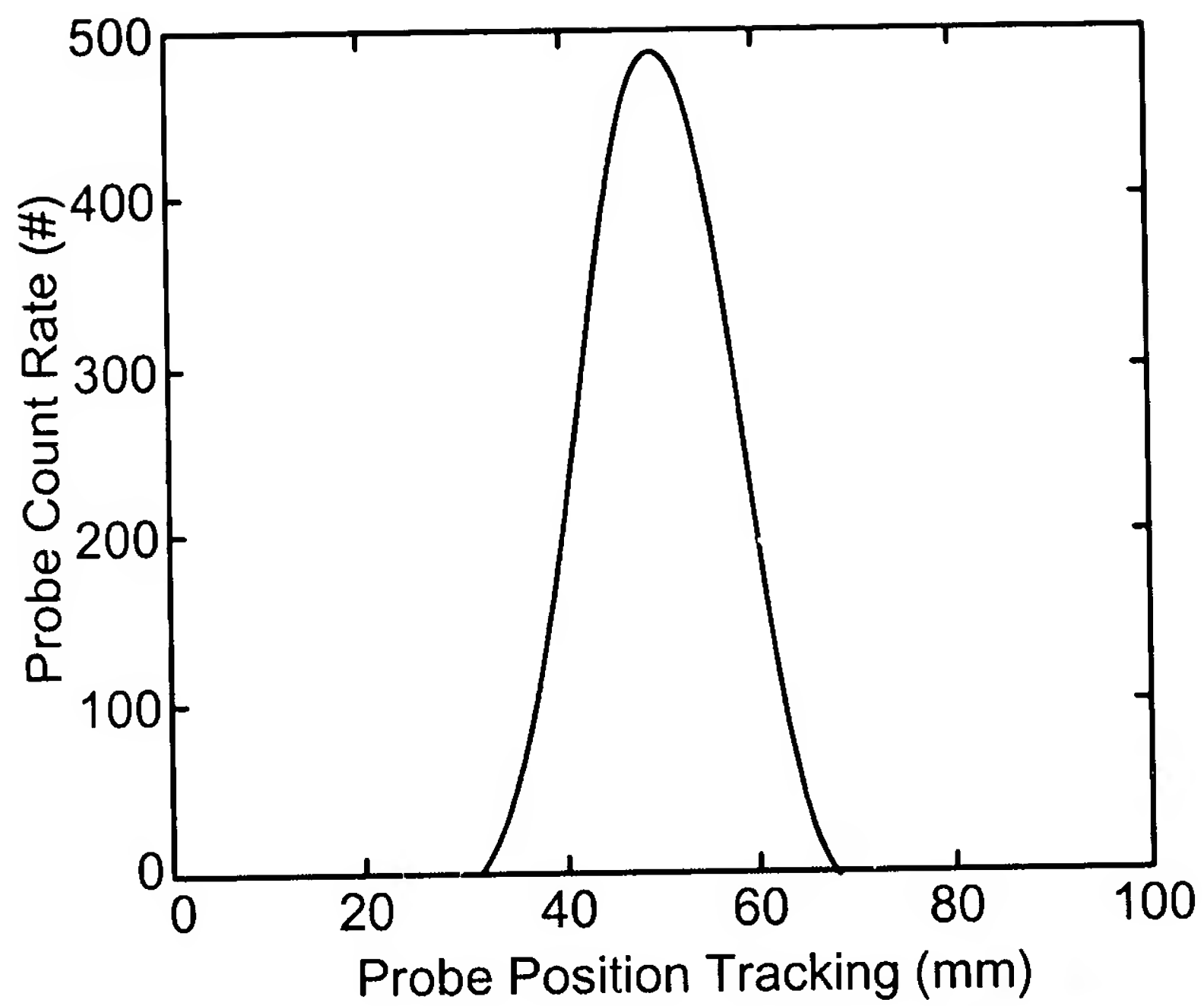


Fig. 16

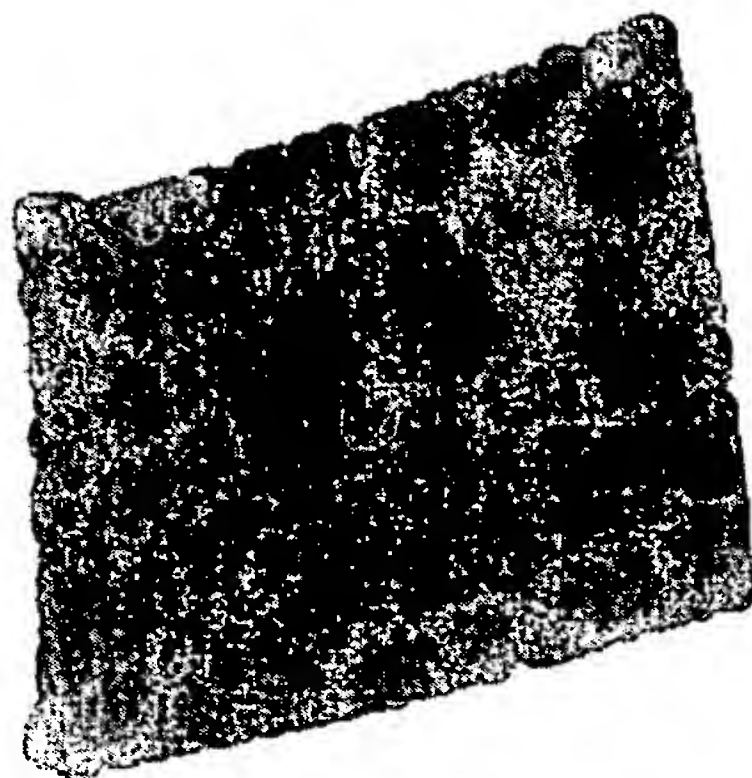


Fig. 17

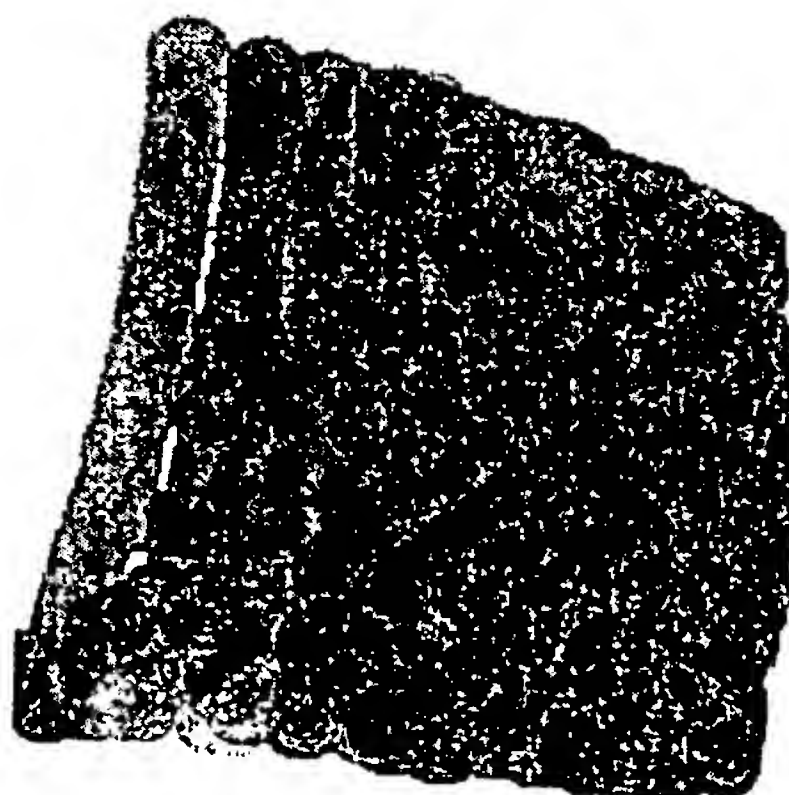


Fig. 18

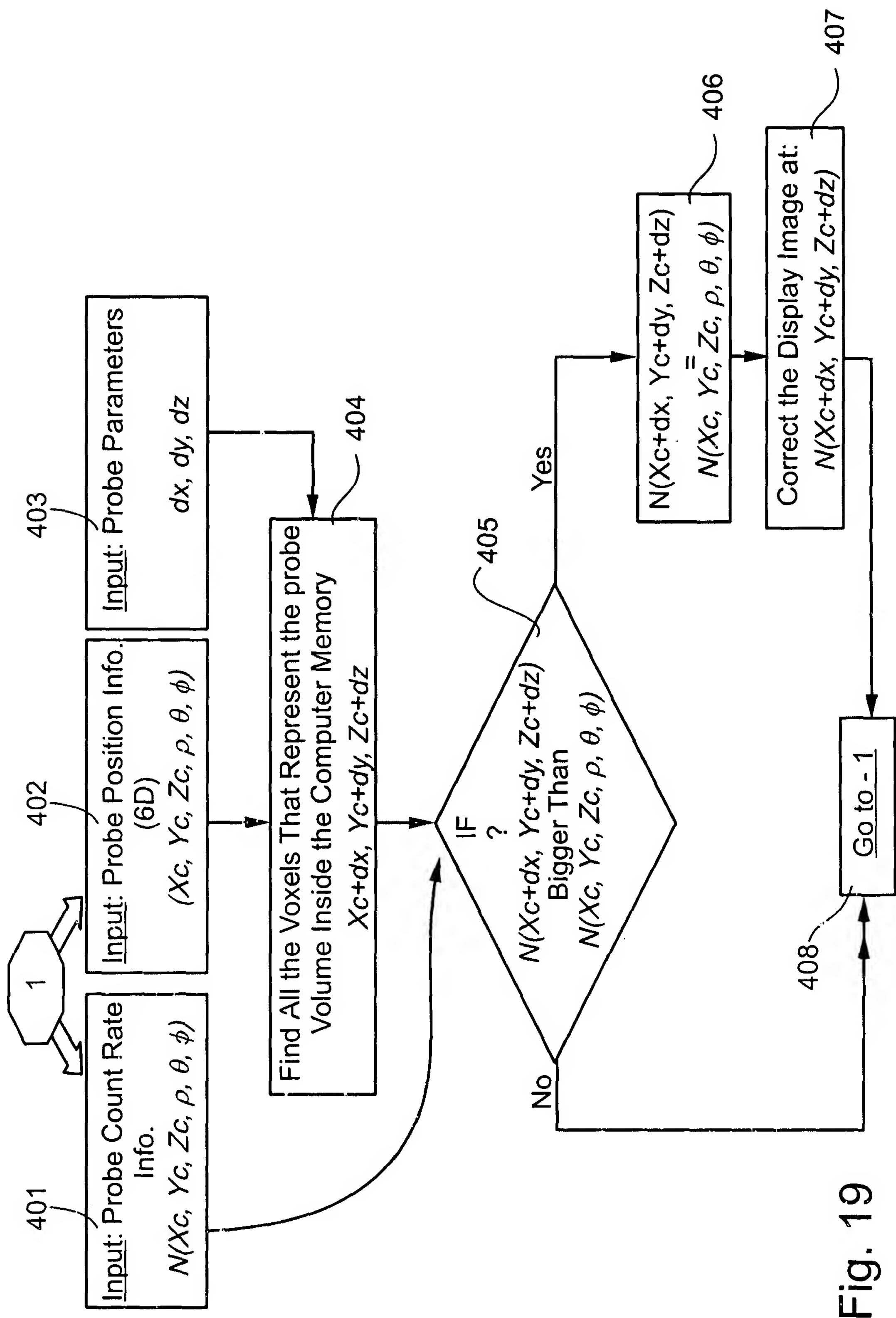


Fig. 19

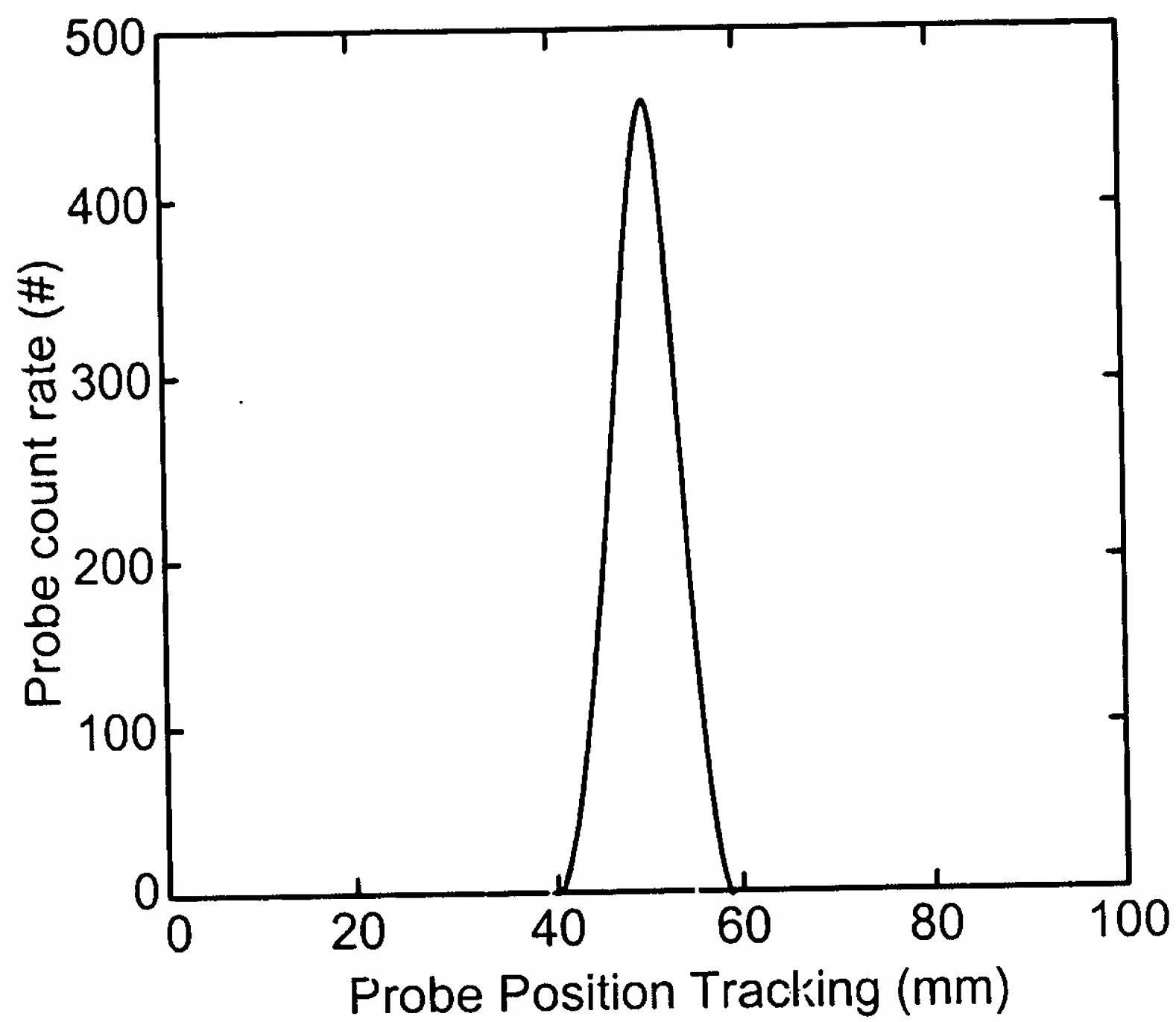


Fig. 20

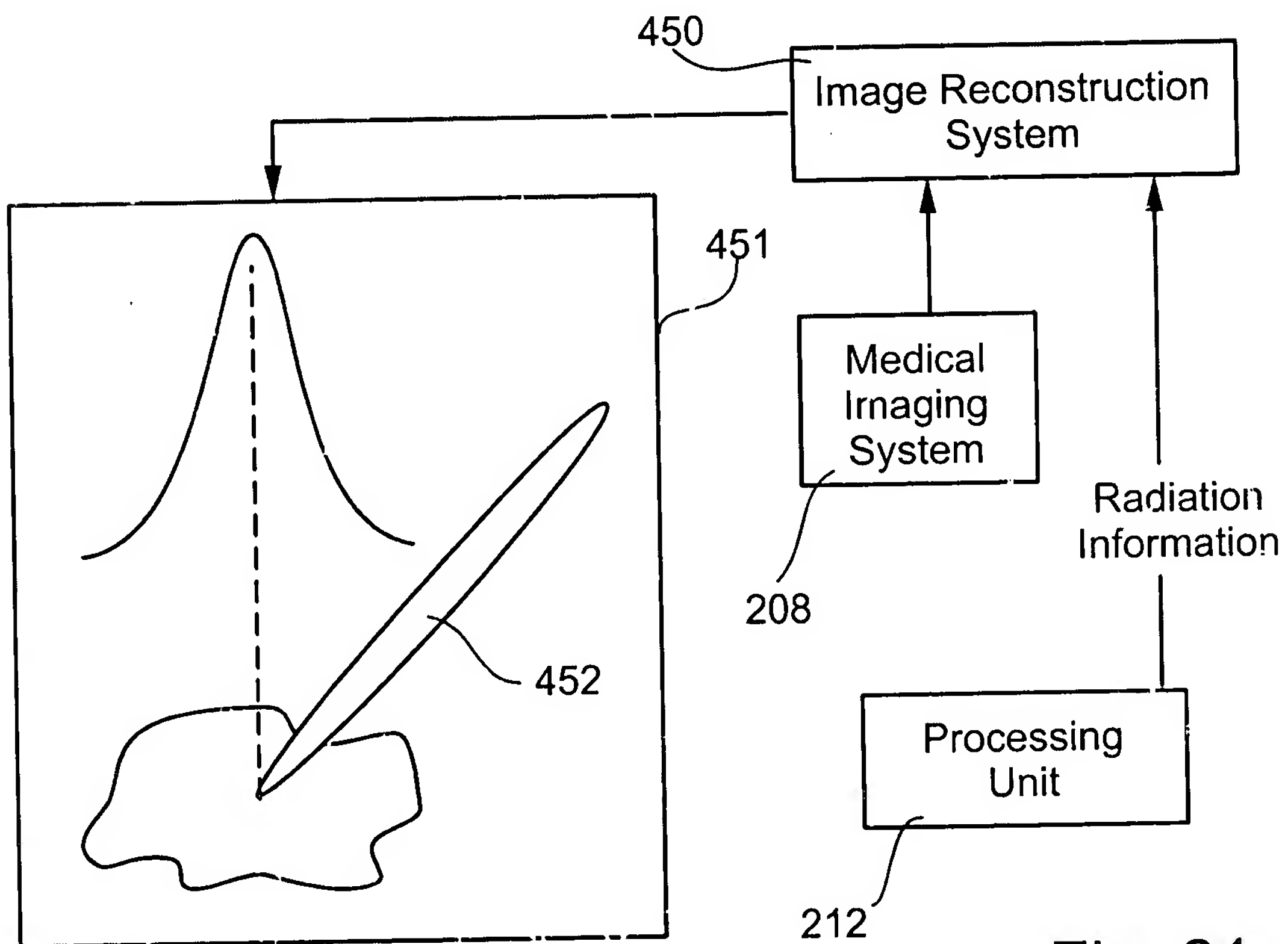


Fig. 21

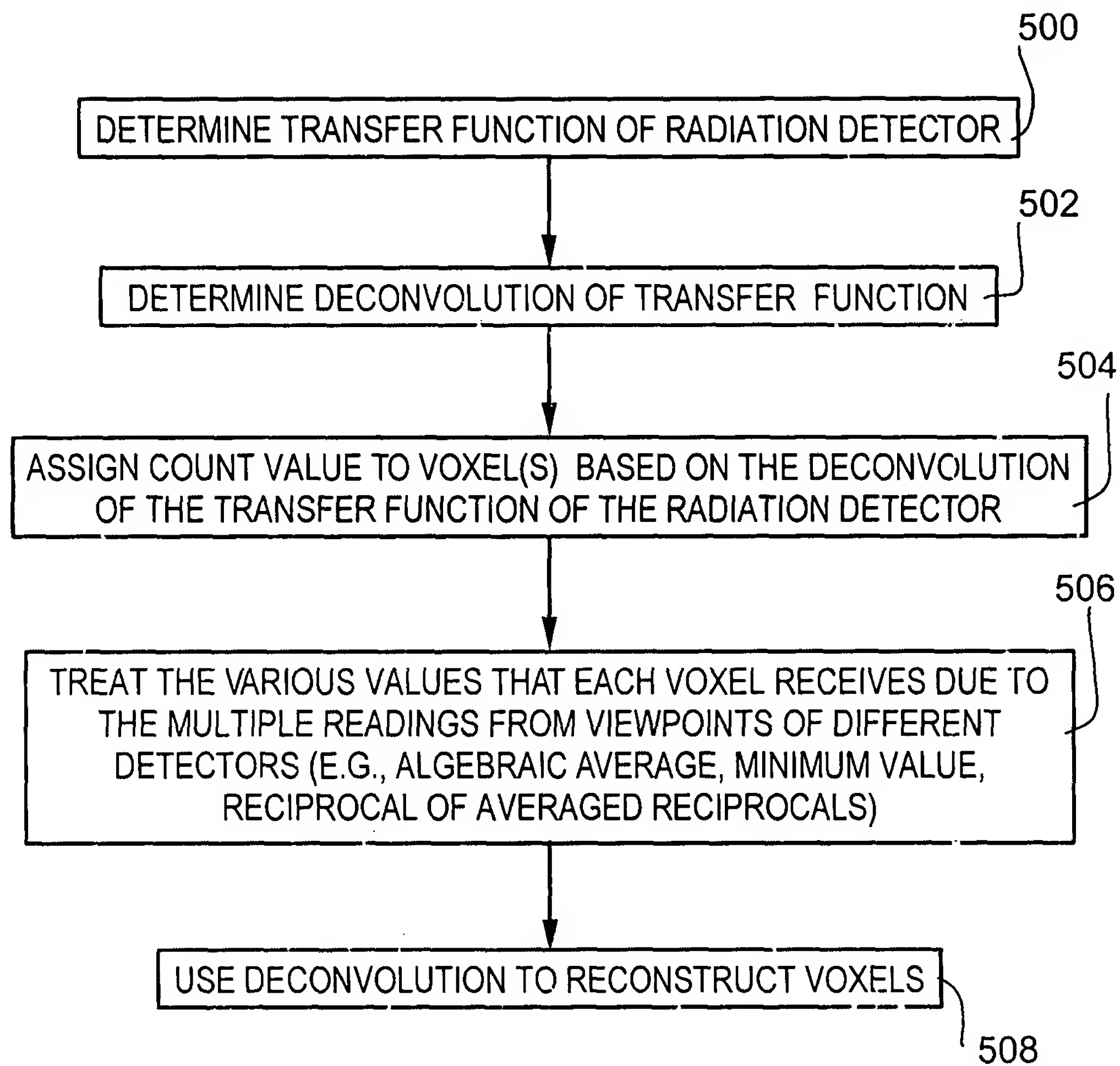


Fig. 22

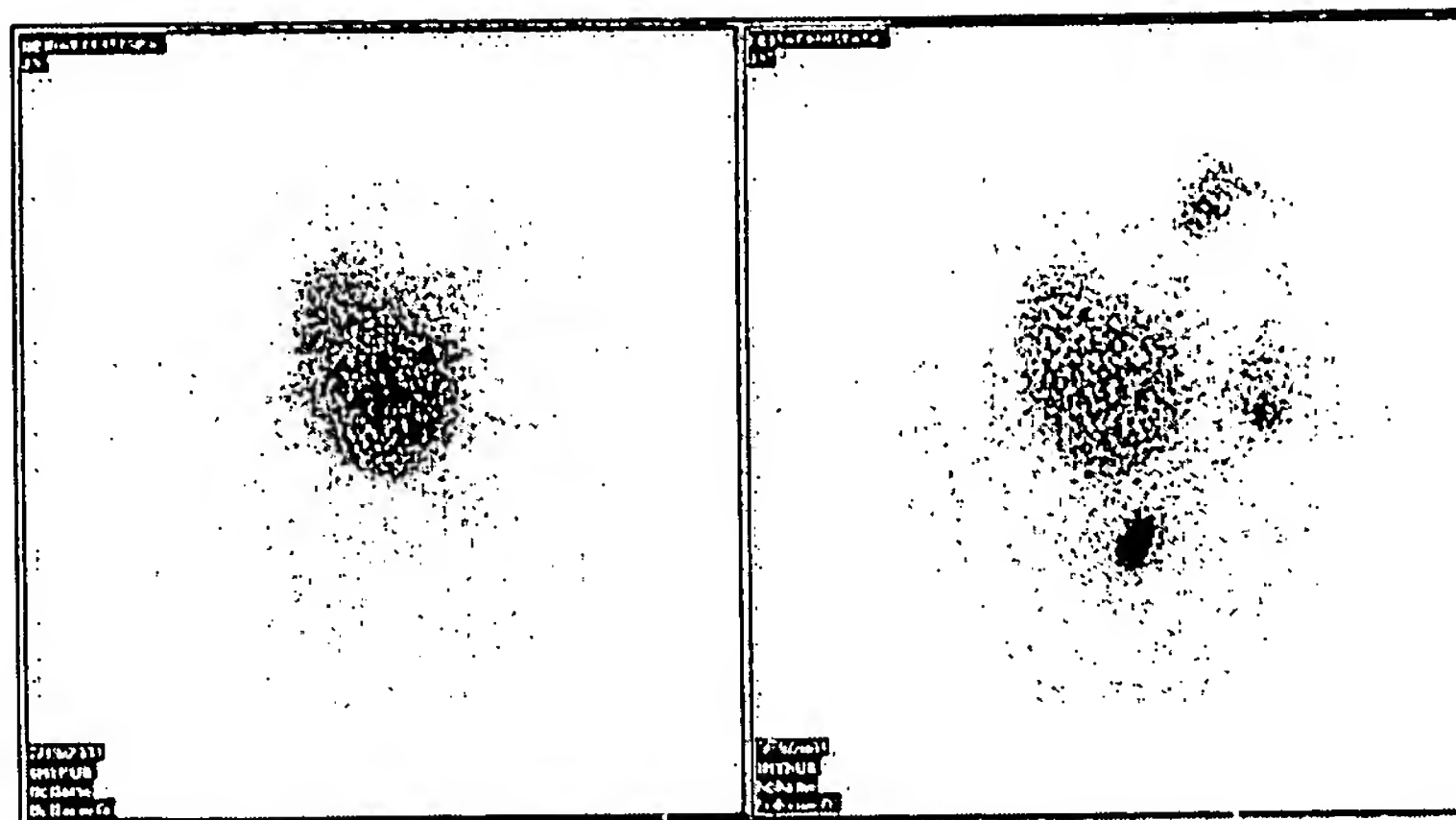


Fig. 23b



Fig. 23a



Fig. 24a

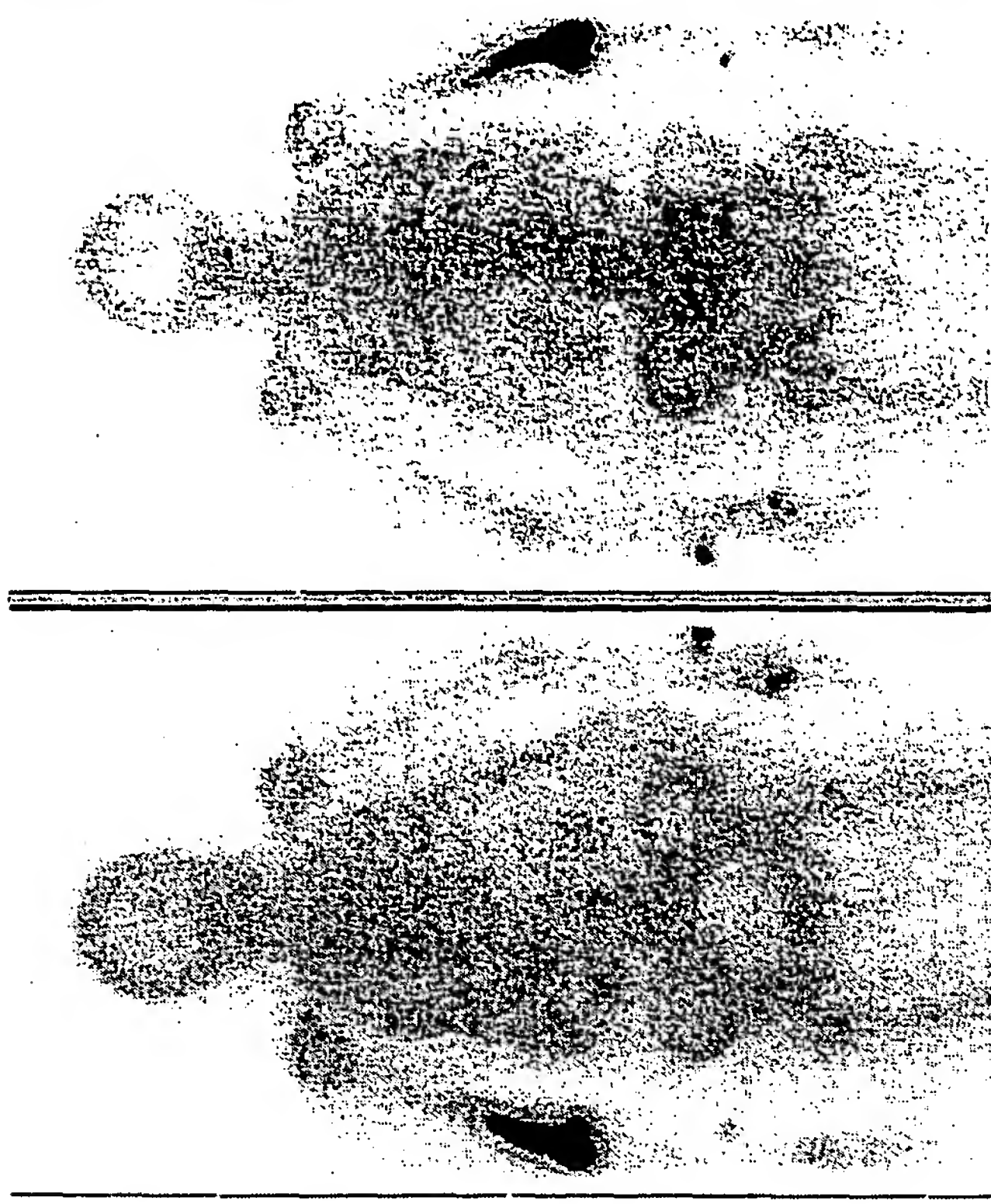


Fig. 24B

Fig. 24b

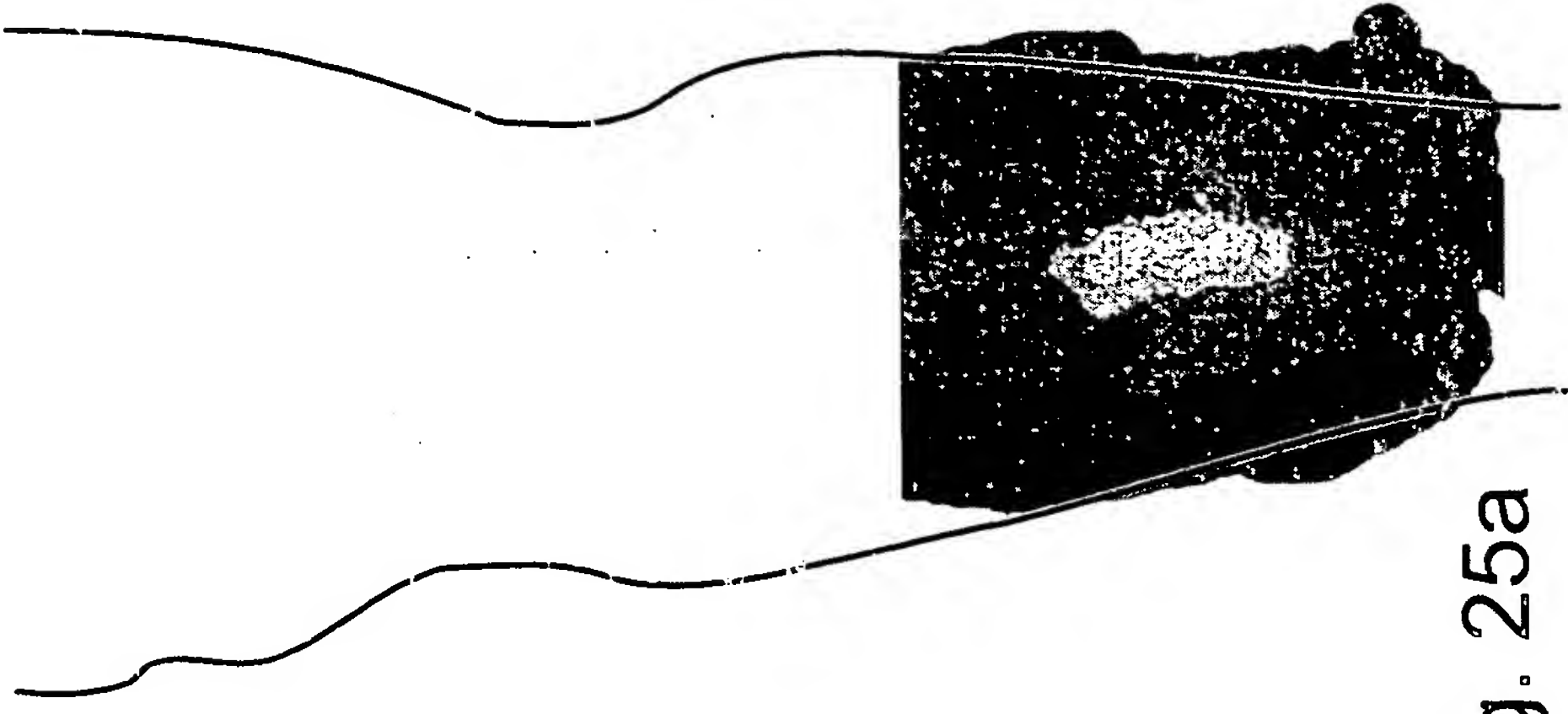


Fig. 25a

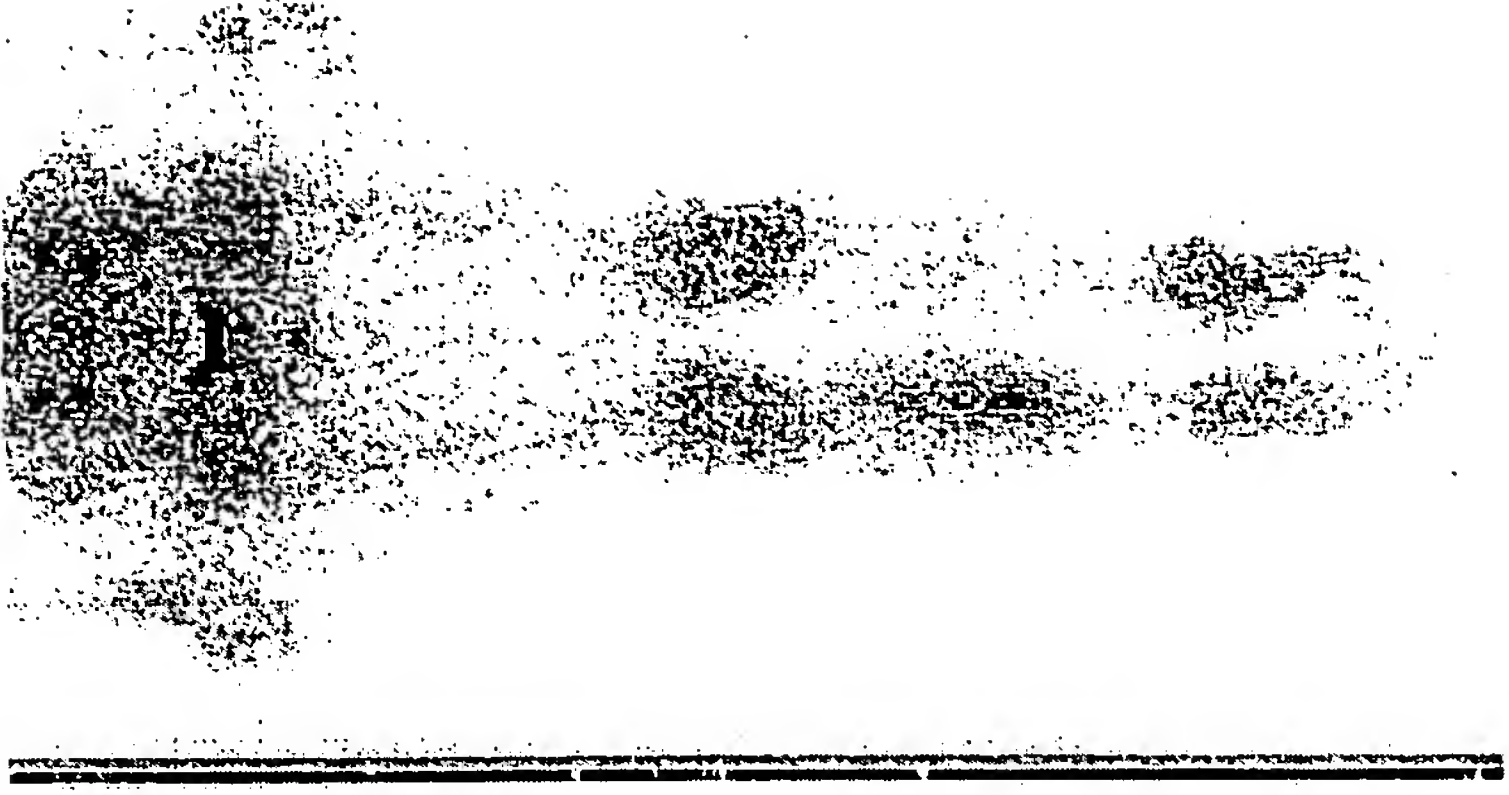
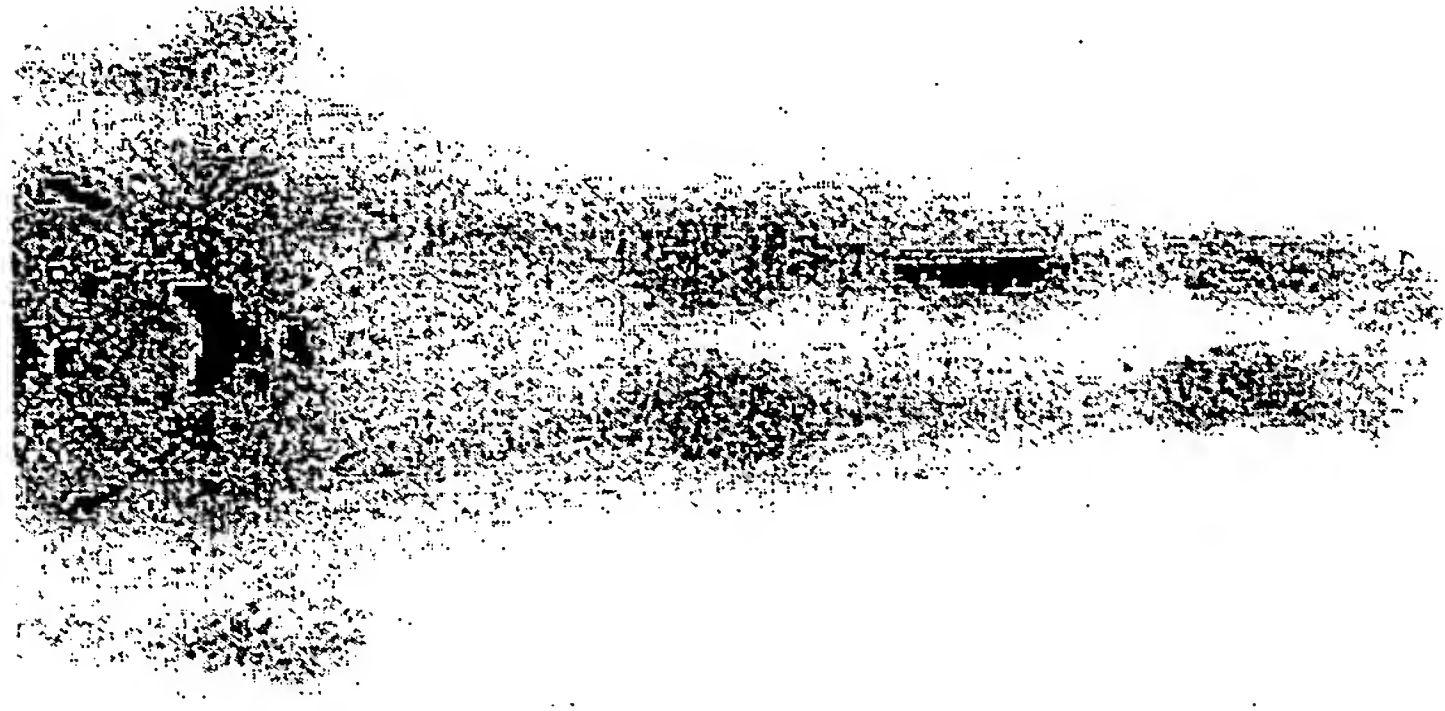


Fig. 25b



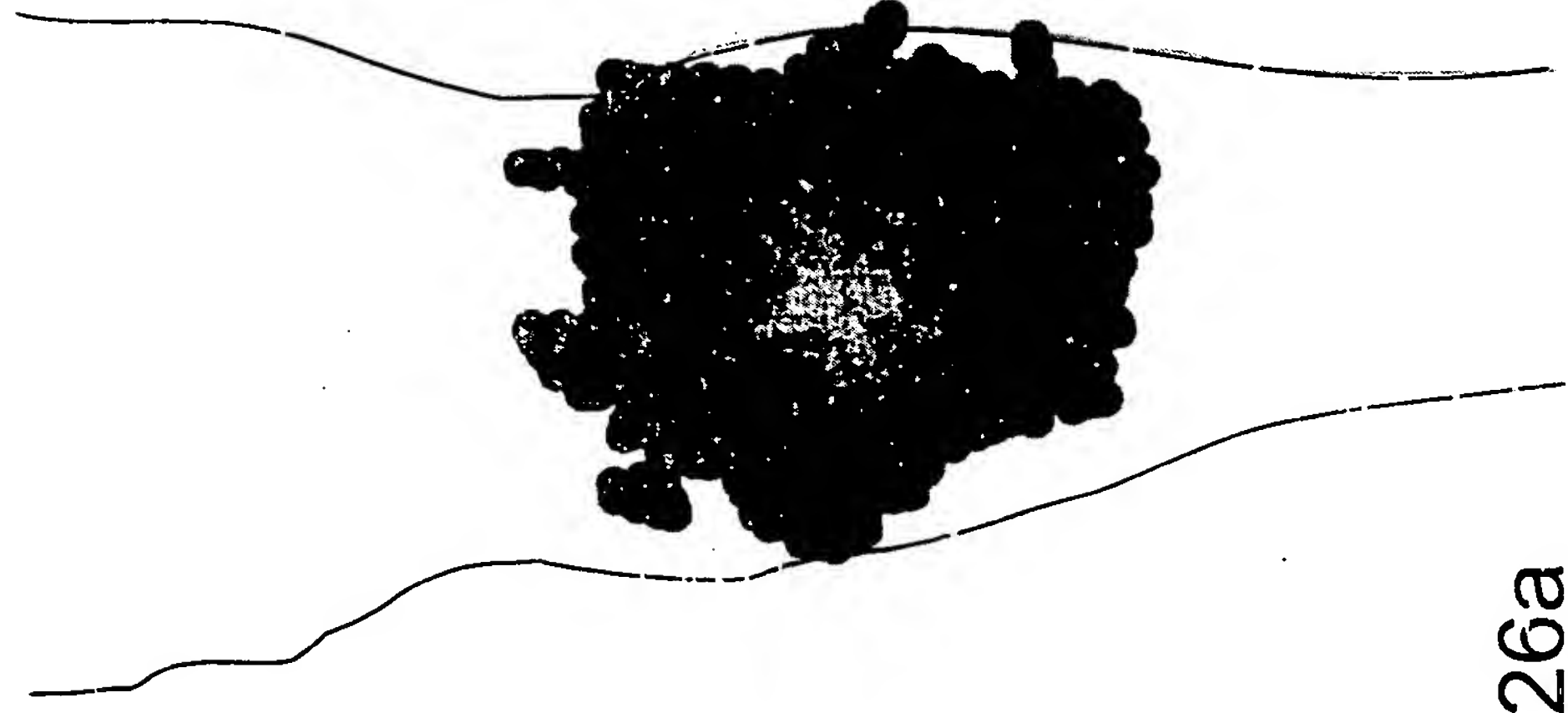


Fig. 26a

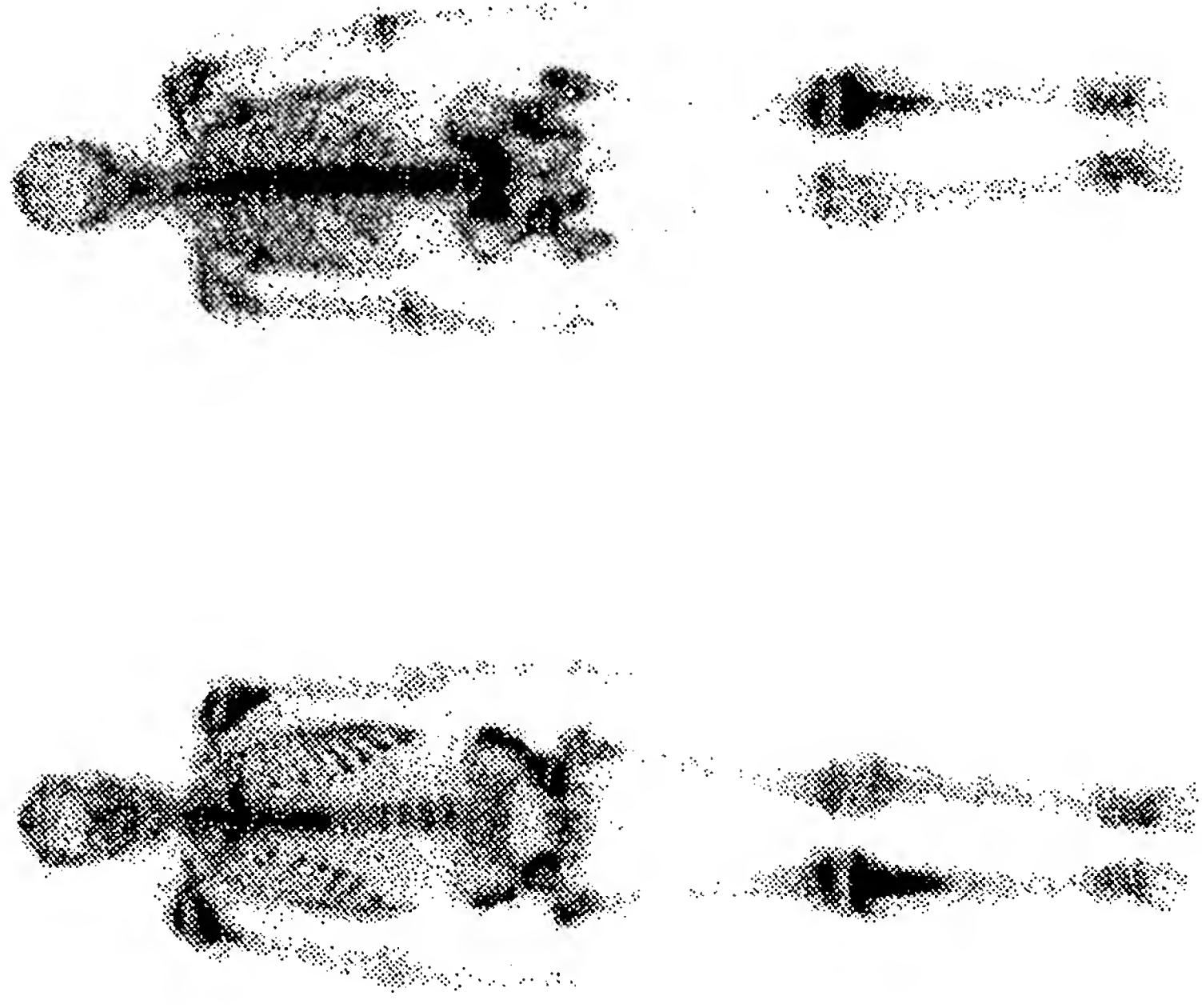


Fig. 26b

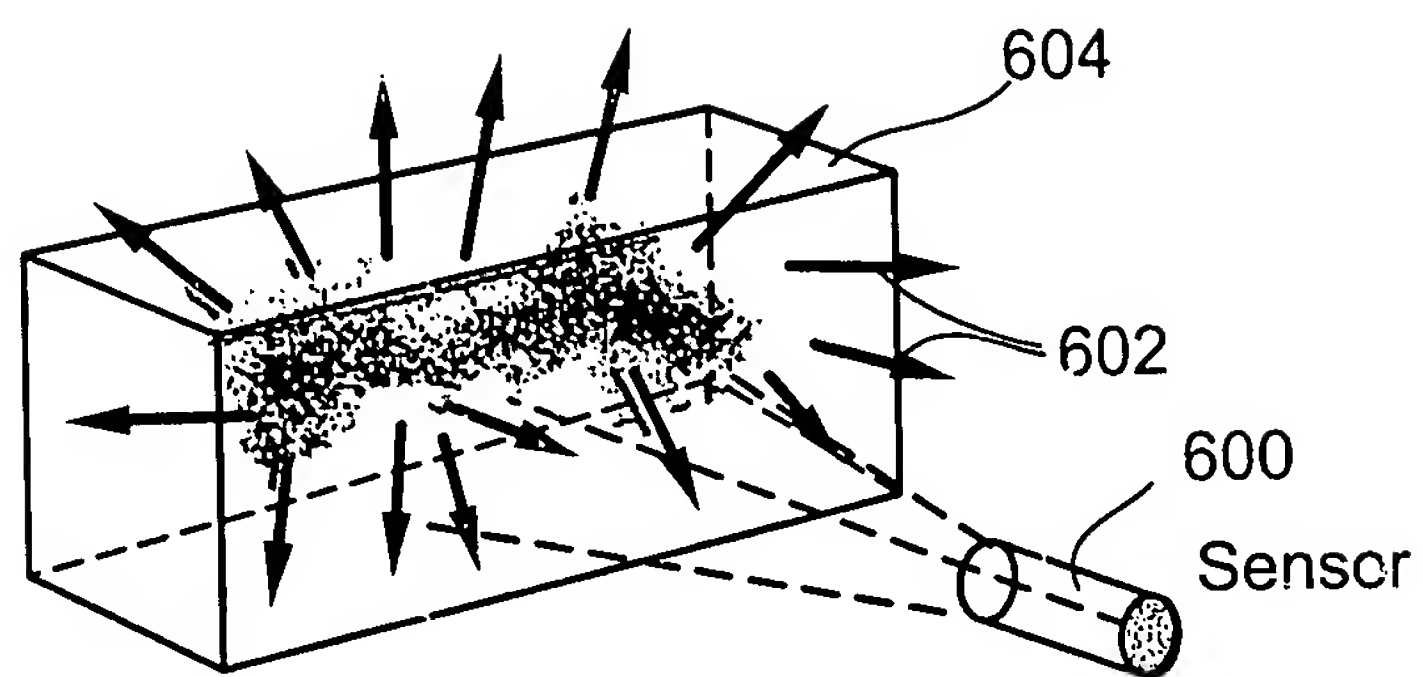


Fig. 27a

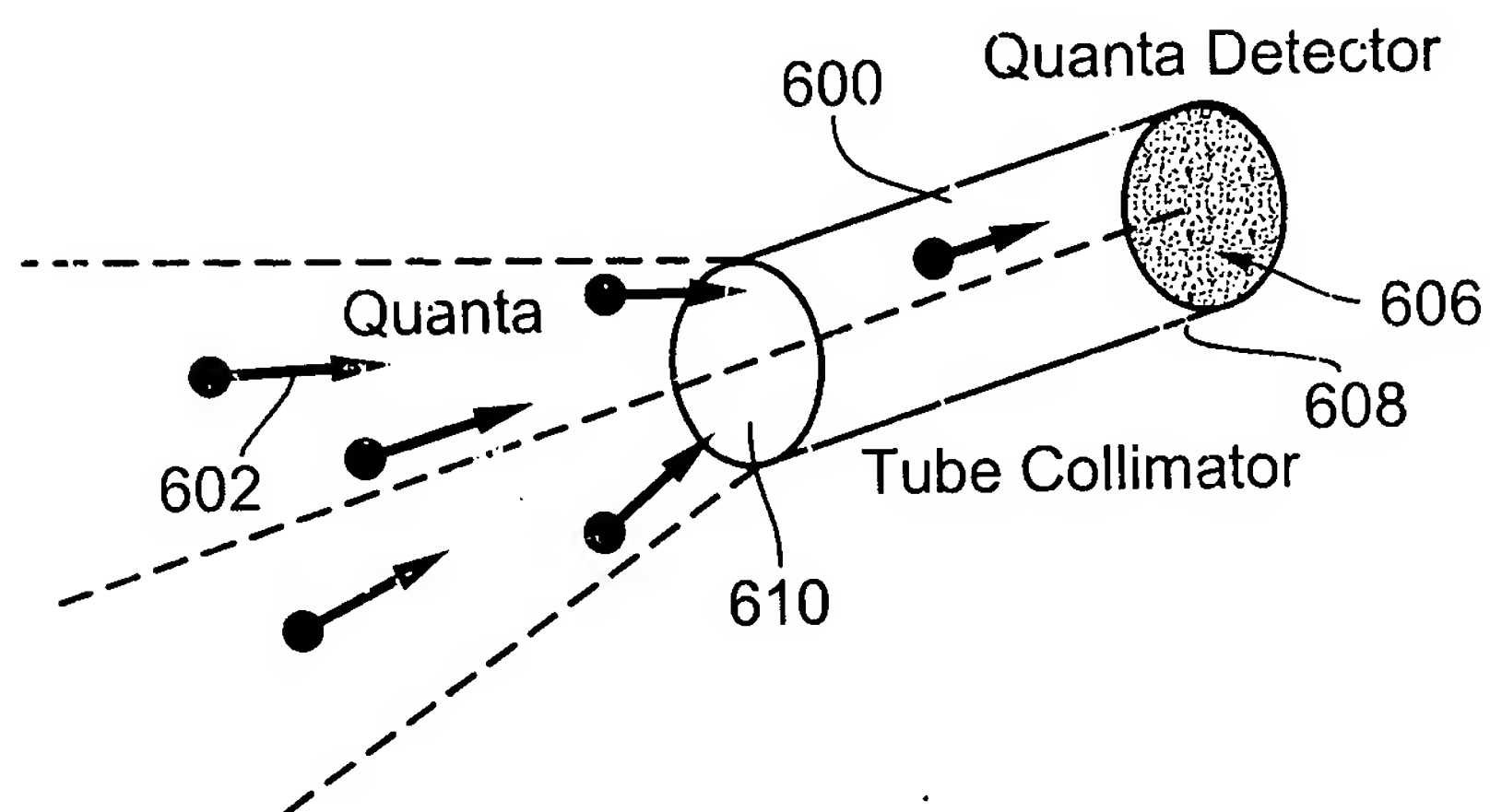


Fig. 27b

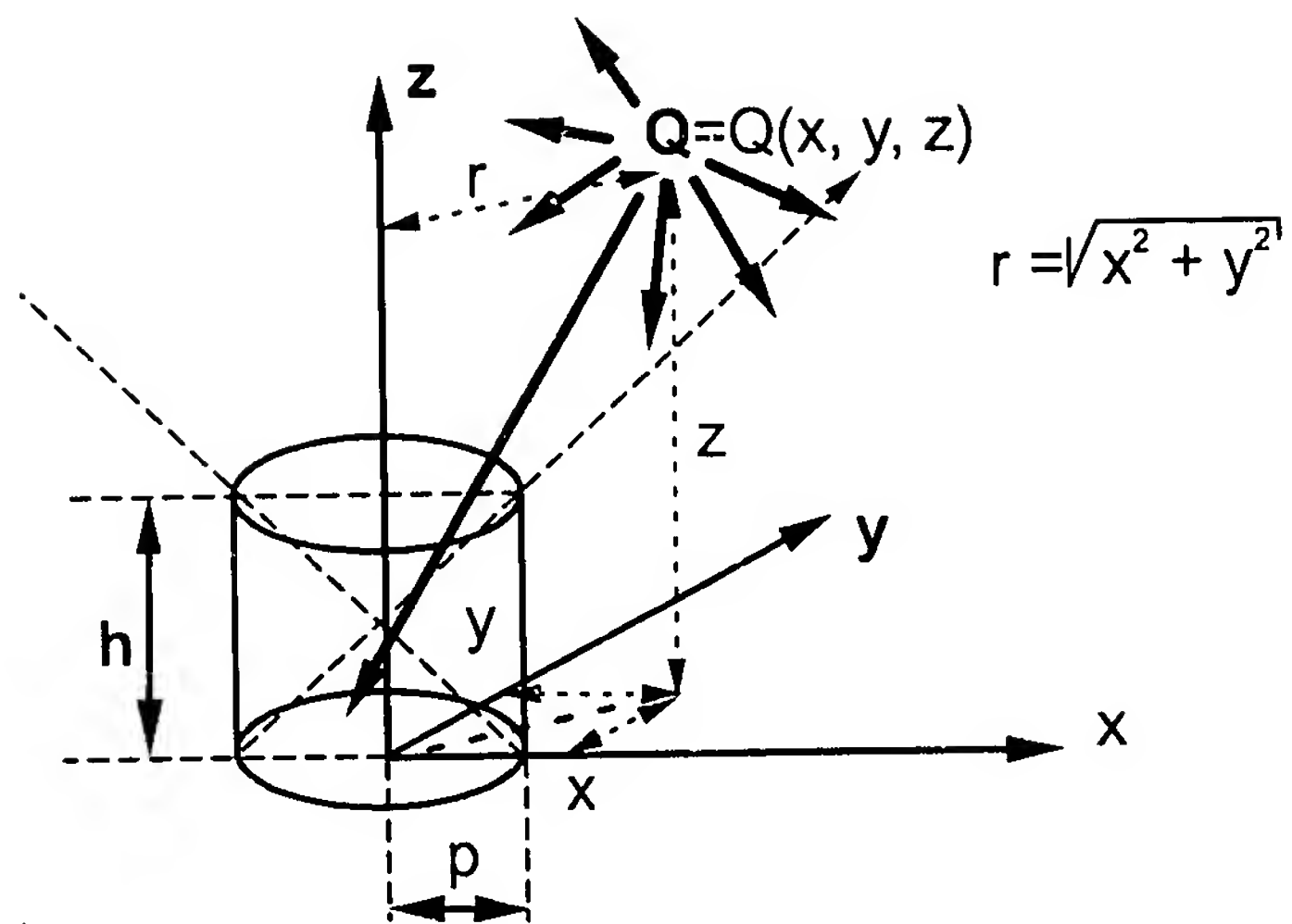


Fig. 27c

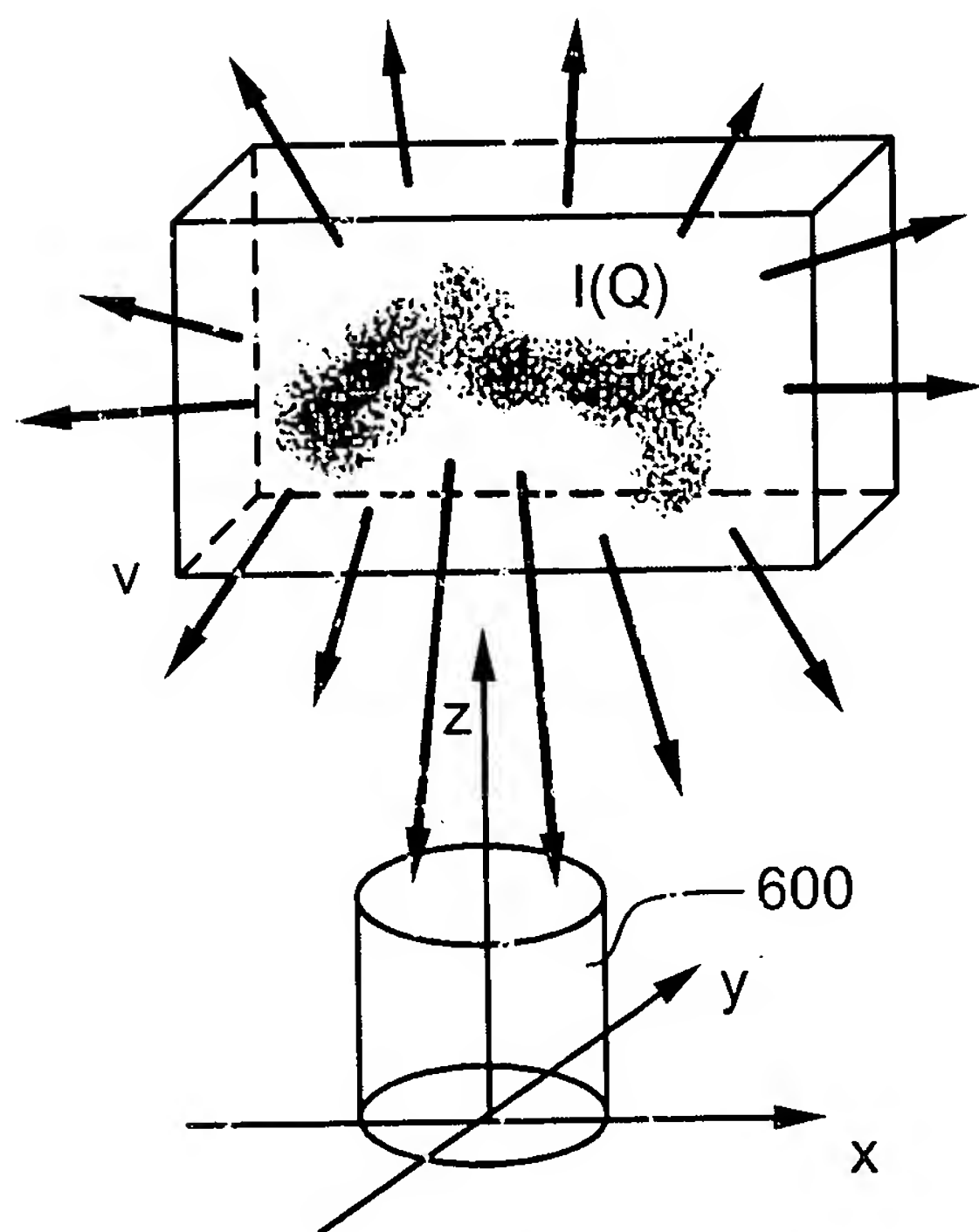


Fig. 27d

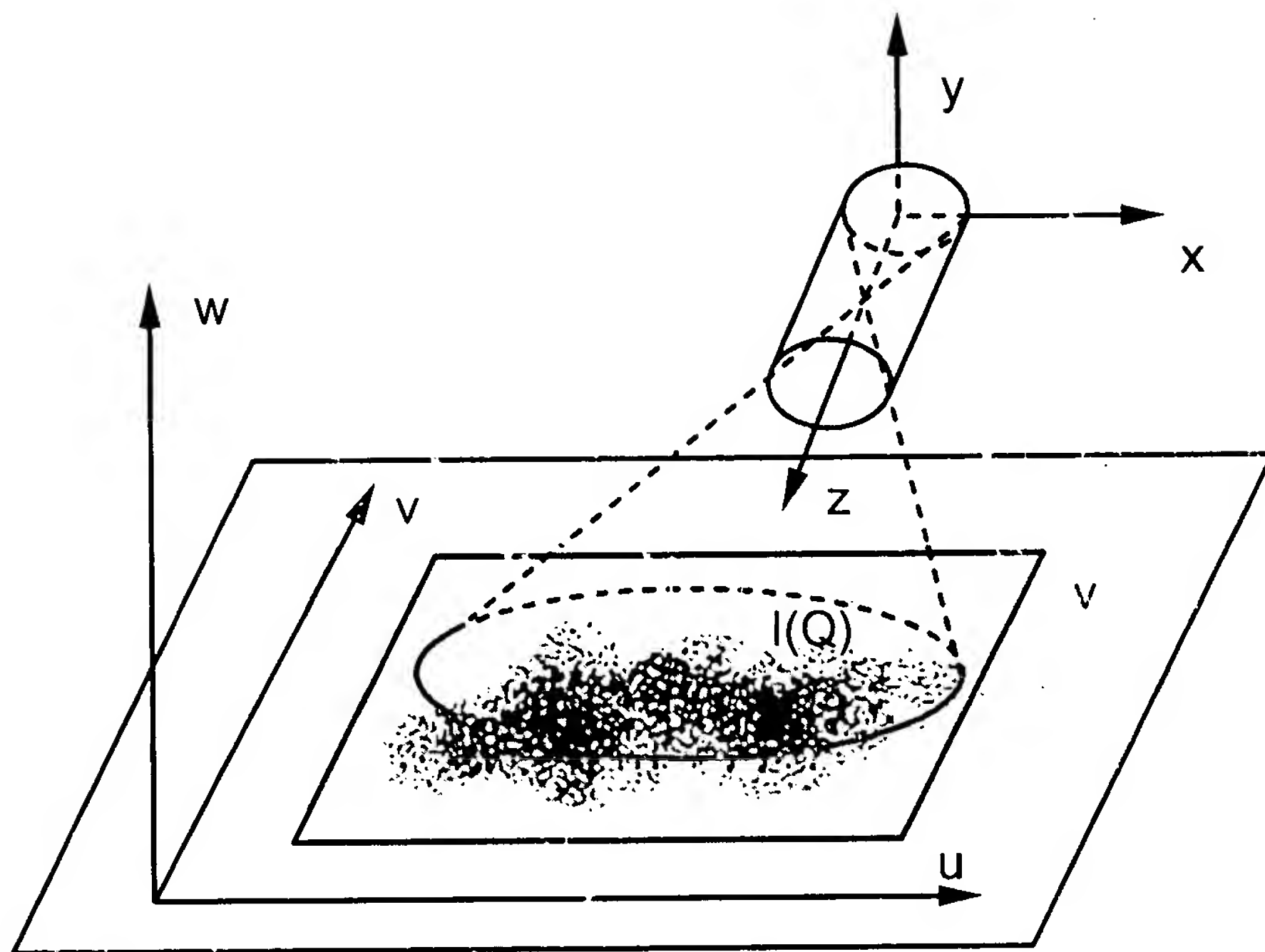


Fig. 27e

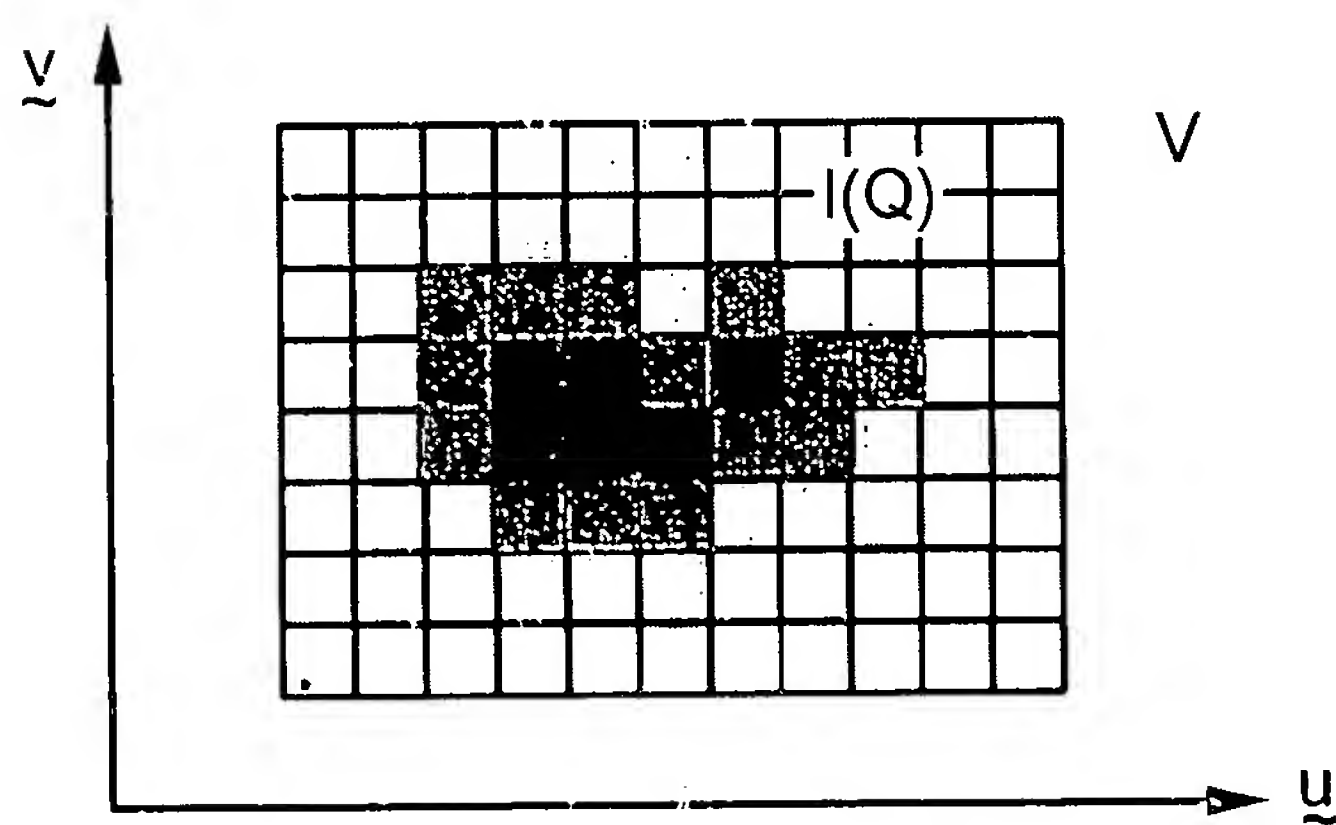


Fig. 27f

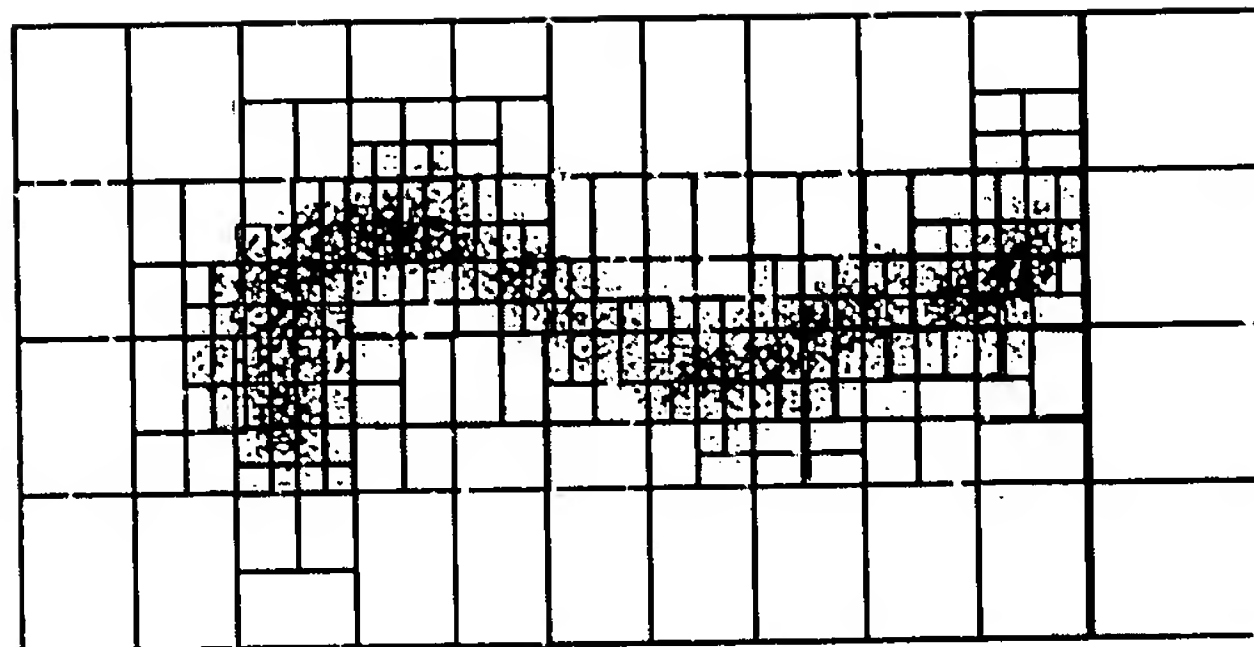


Fig. 27g

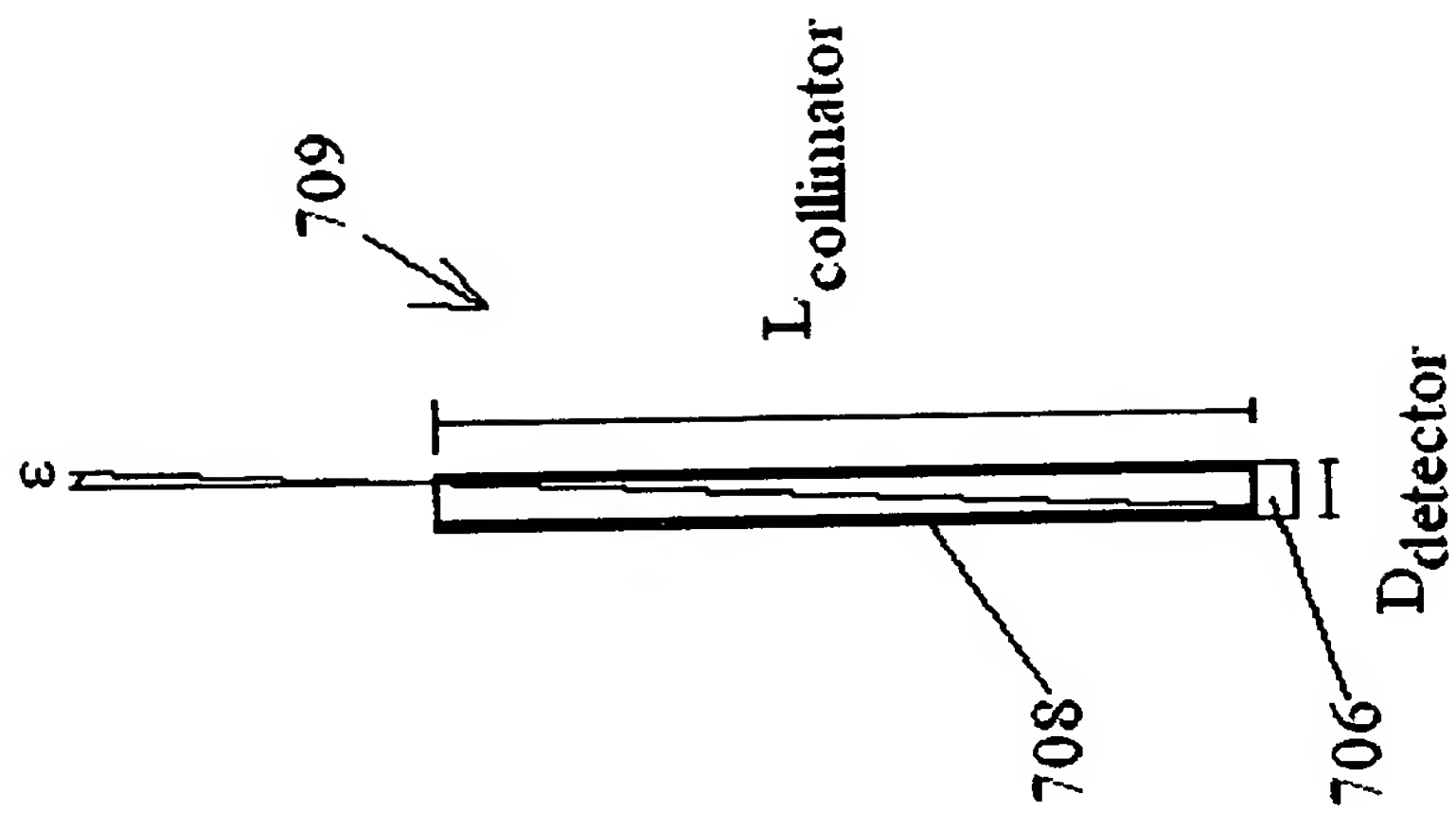


Figure 27I

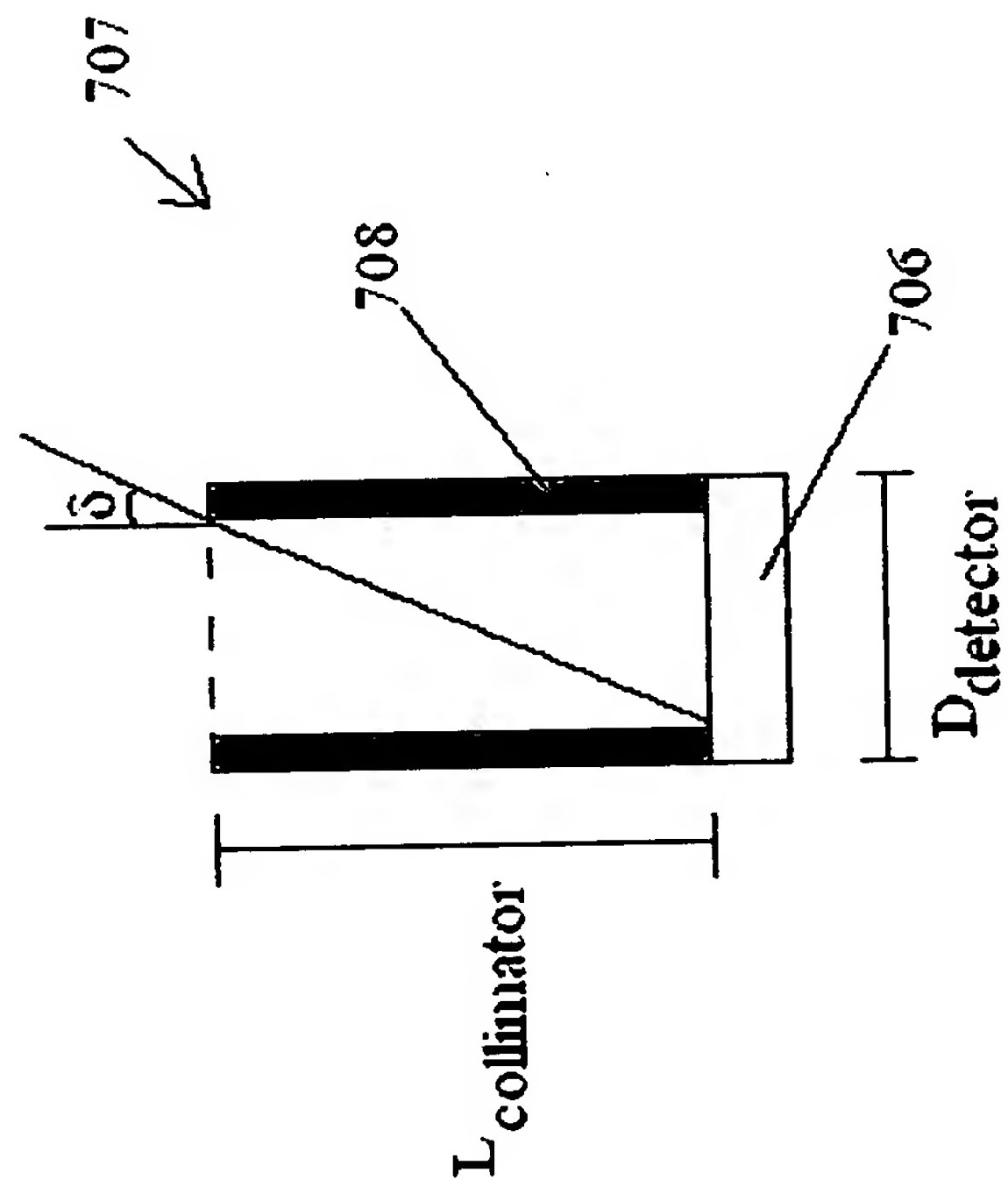


Figure 27H

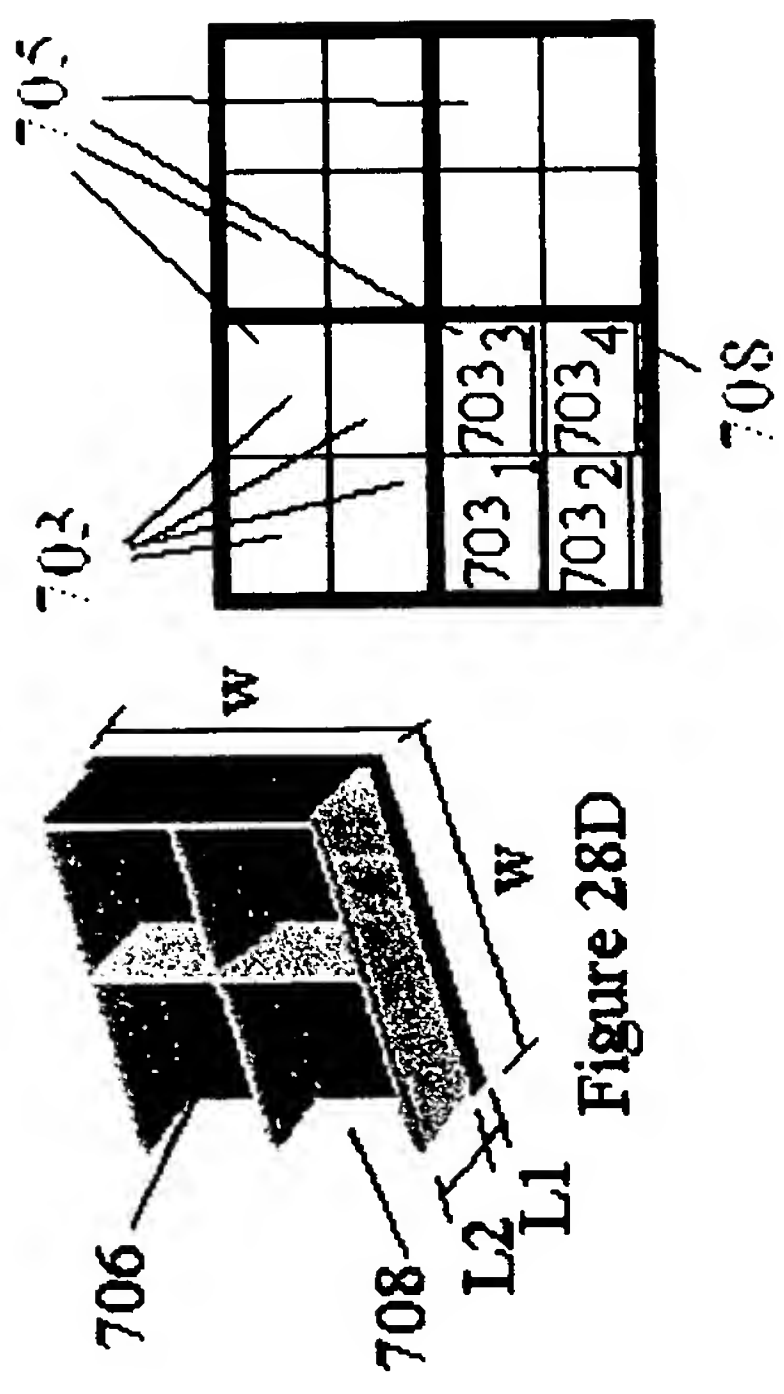


Figure 28E

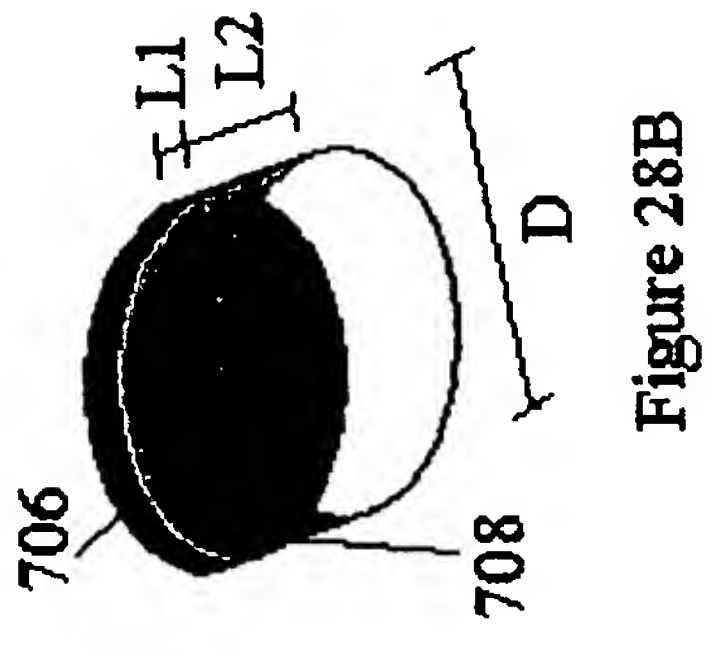
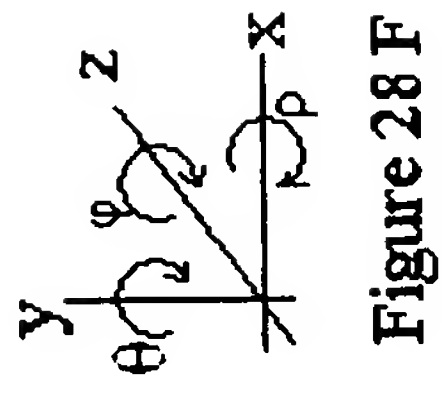


Figure 28B

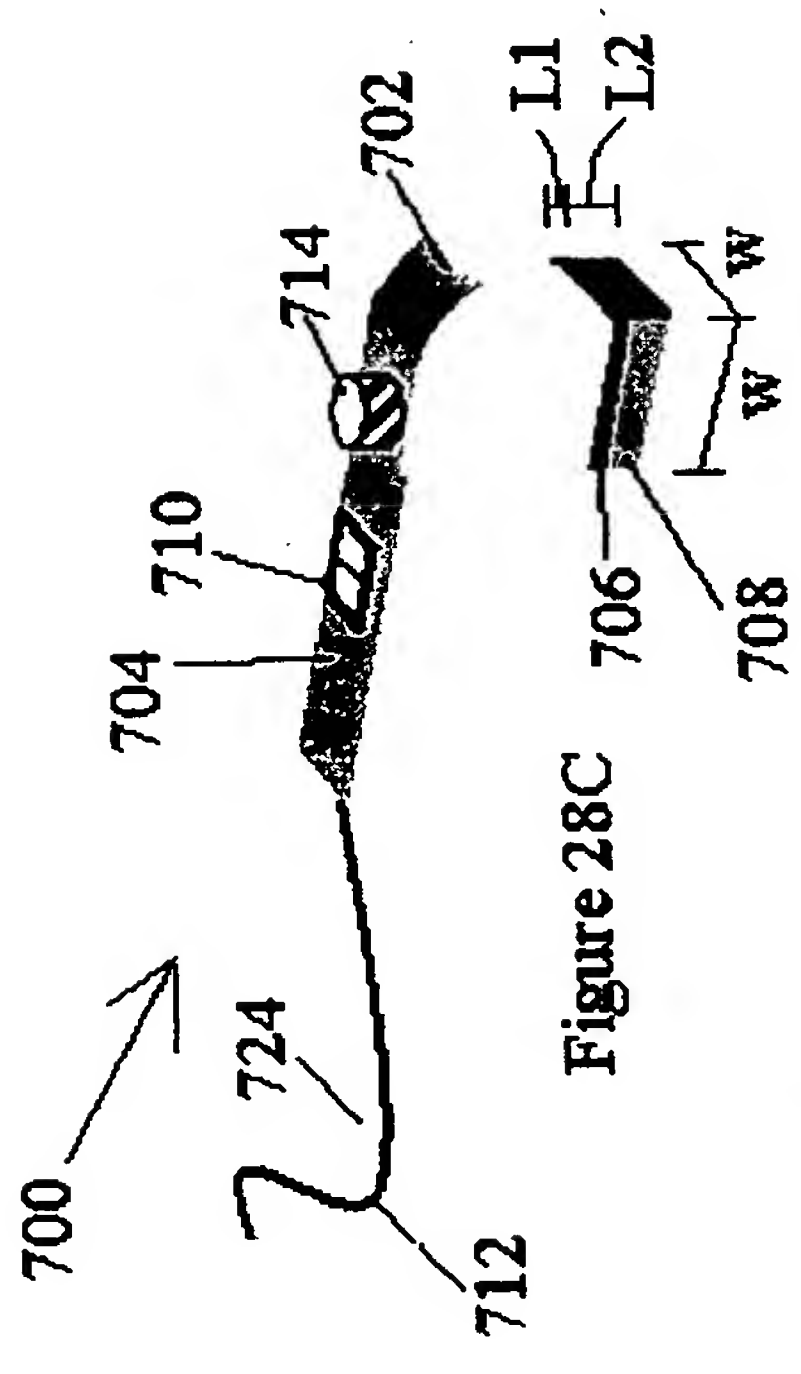


Figure 28C

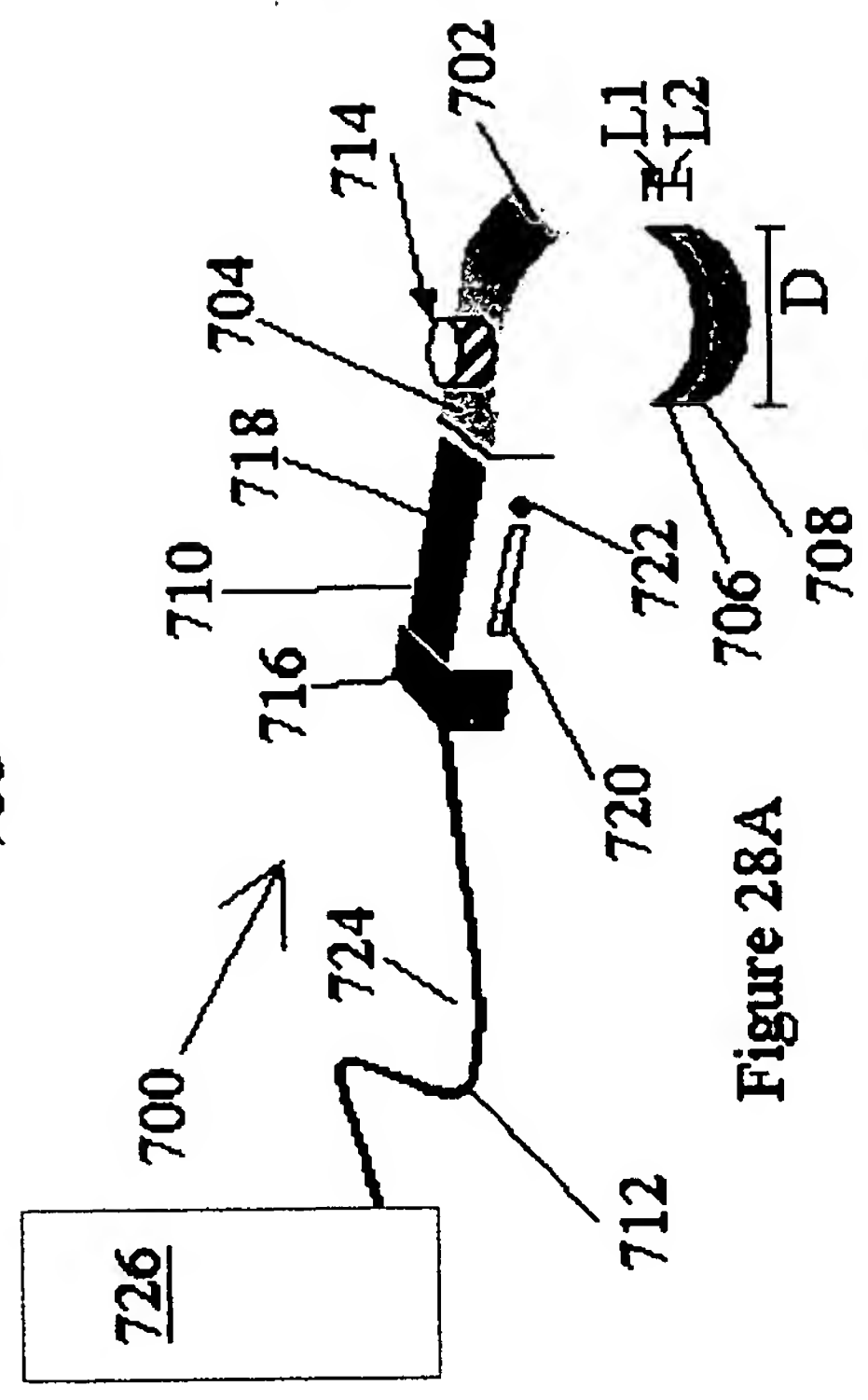


Figure 28A

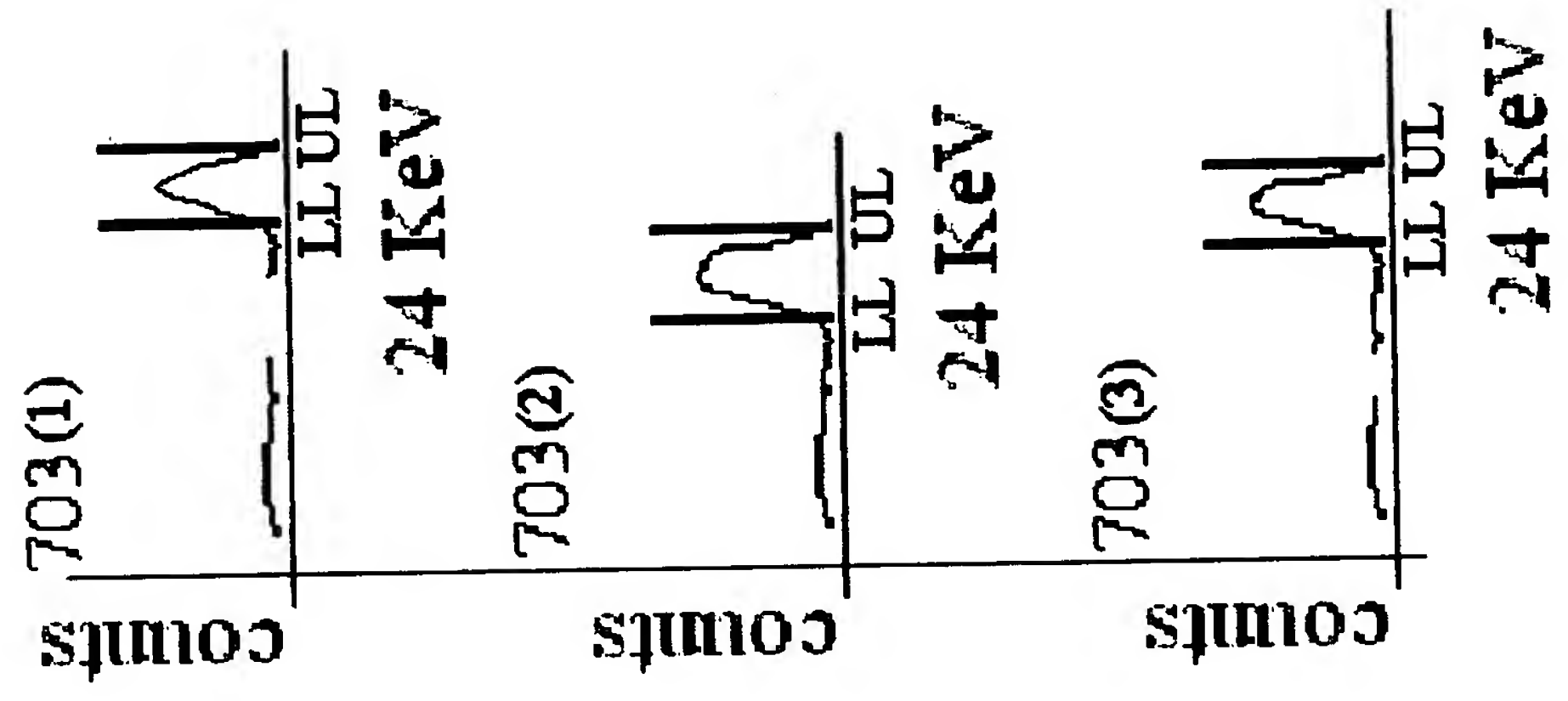


Figure 29B

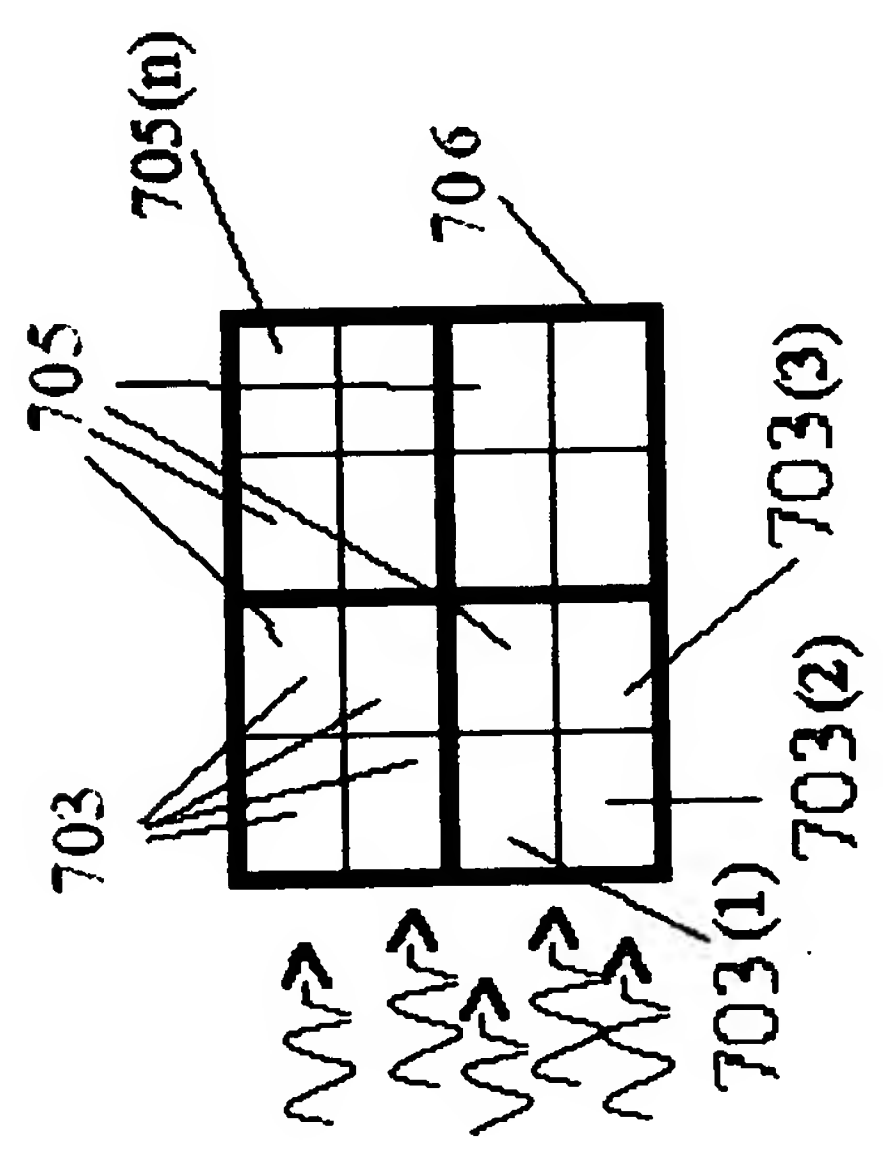
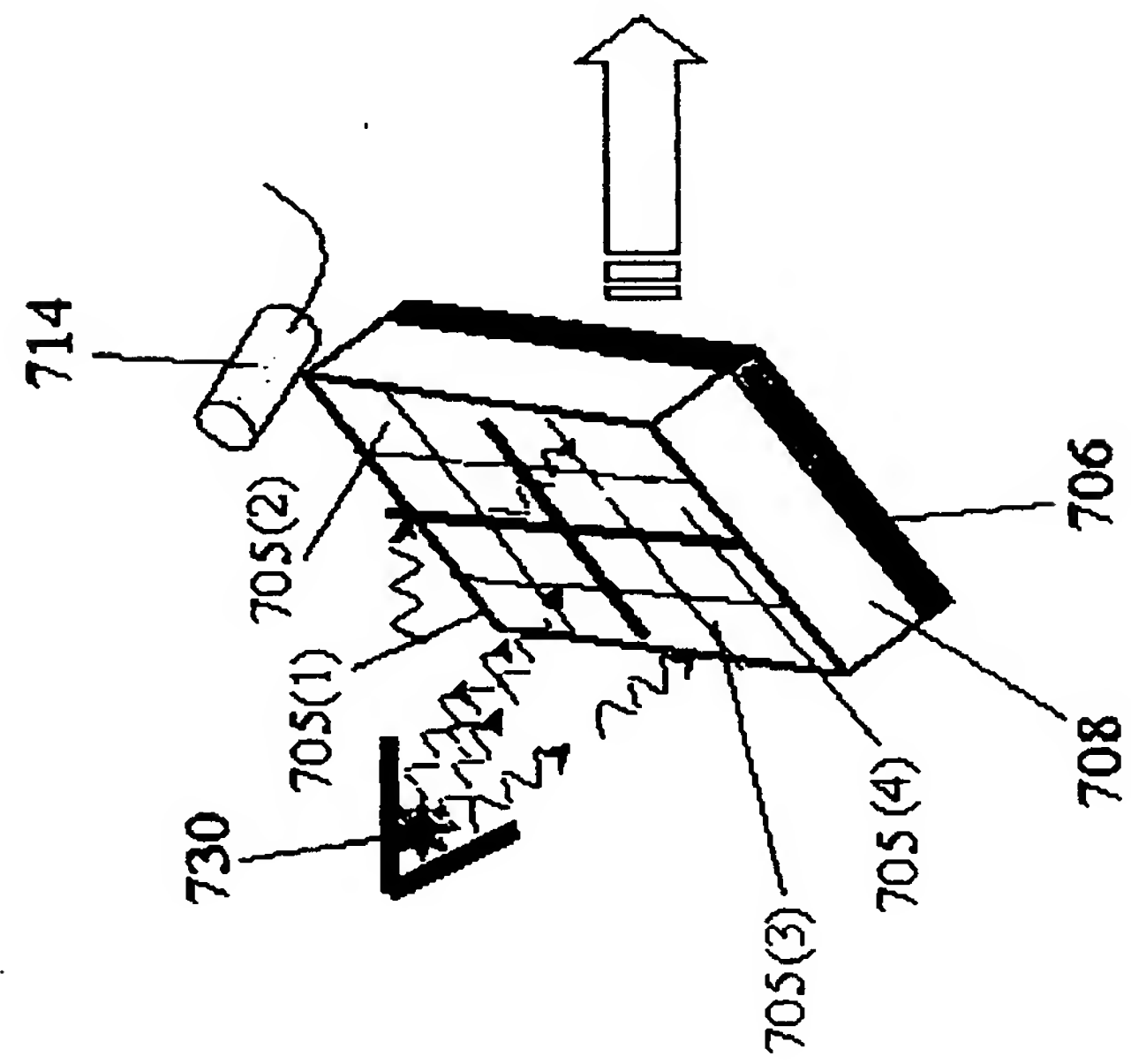


Figure 29A





Time [msec]	Counts/sec				Position
	705(1)	705(2)	705(3)	705(4)	
$t_1 = 100$	503	107	11	9	$(X; Y; Z; \rho; \theta; \phi)_{t1}$
$t_2 = 200$	482	91	15	3	$(X; Y; Z; \rho; \theta; \phi)_{t2}$
$t_3 = 300$	491	101	13	4	$(X; Y; Z; \rho; \theta; \phi)_{t3}$
.	.	.	.	.	.
.	.	.	.	.	.

Figure 30

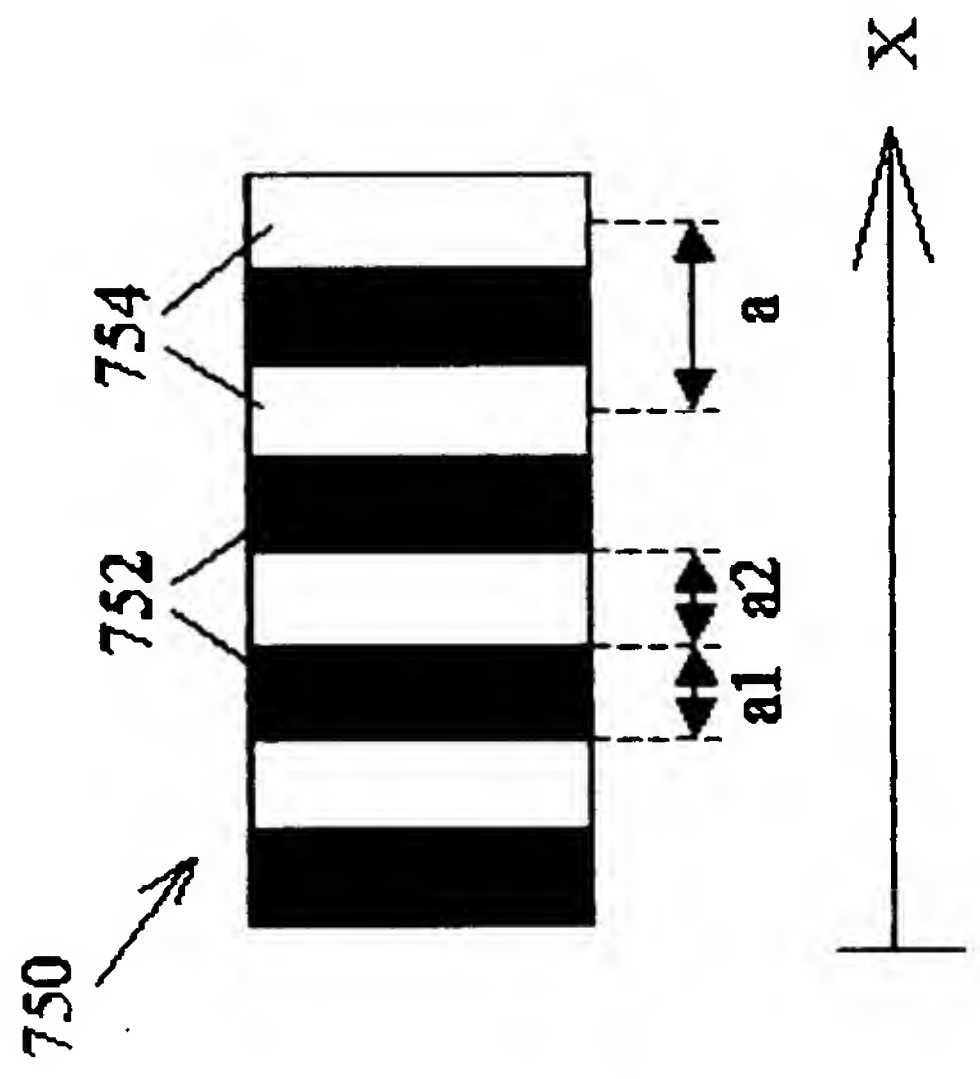


Figure 31A

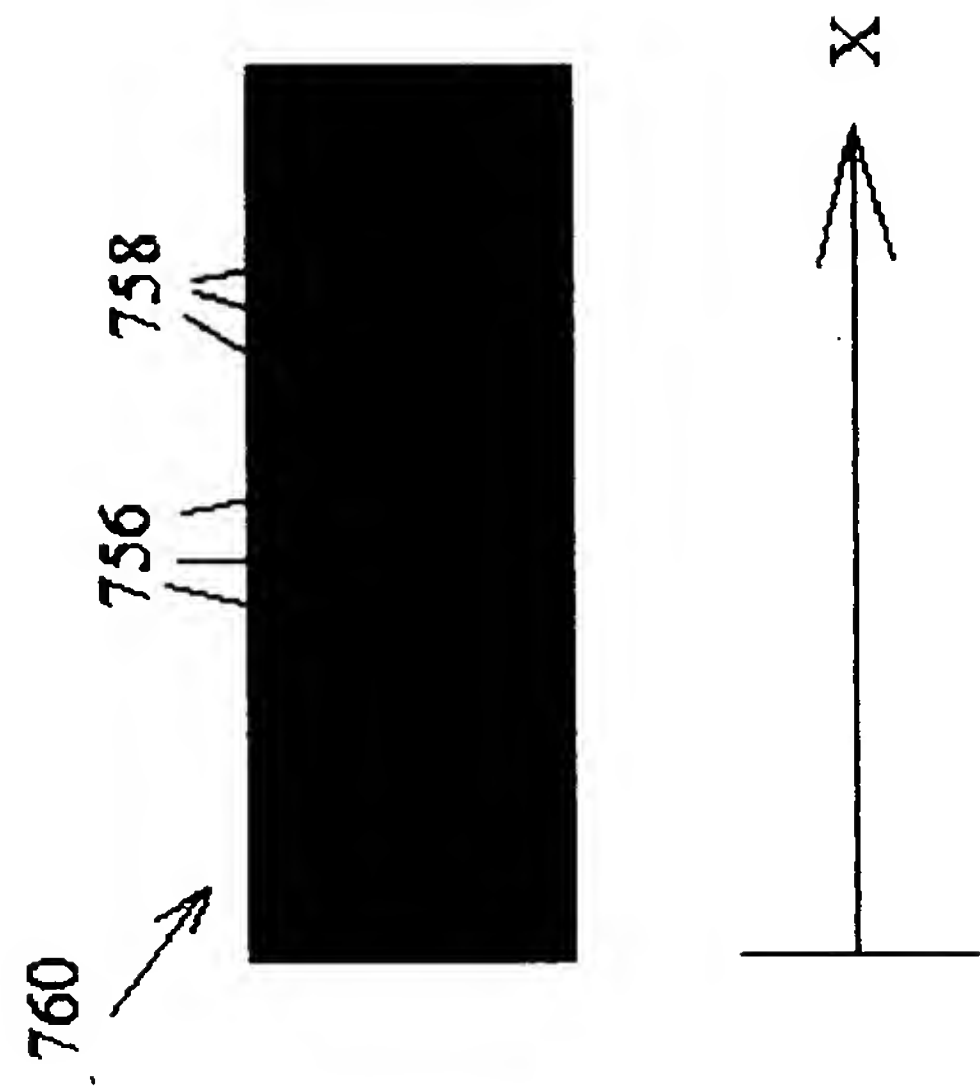


Figure 31B

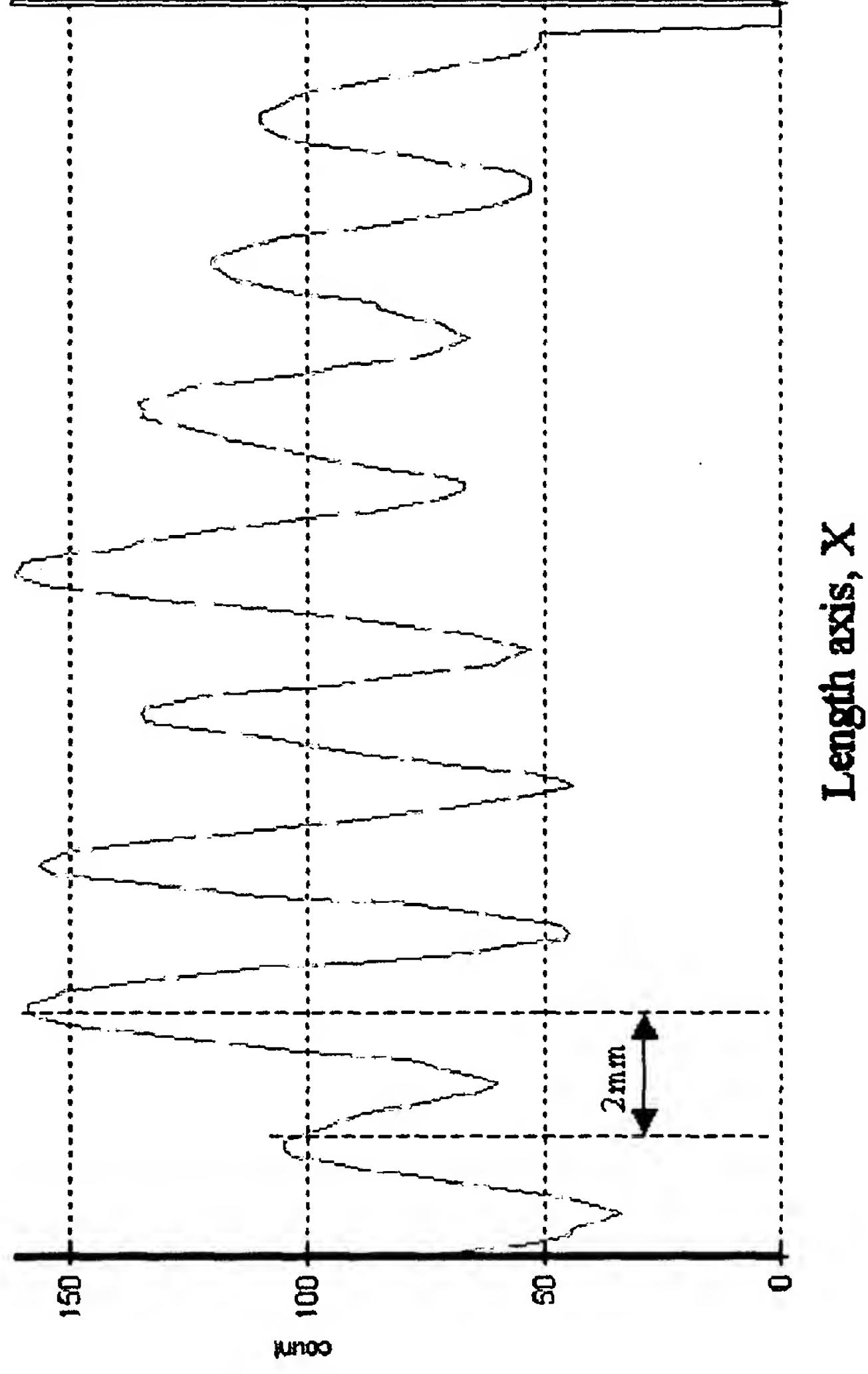


Figure 31 C

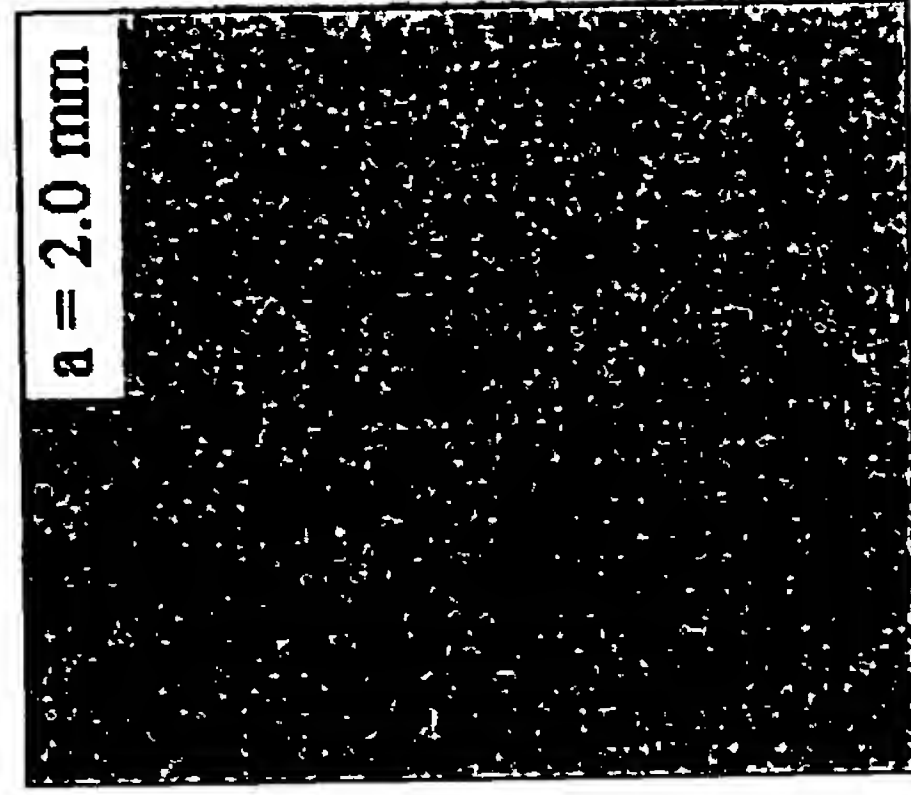


Figure 32A

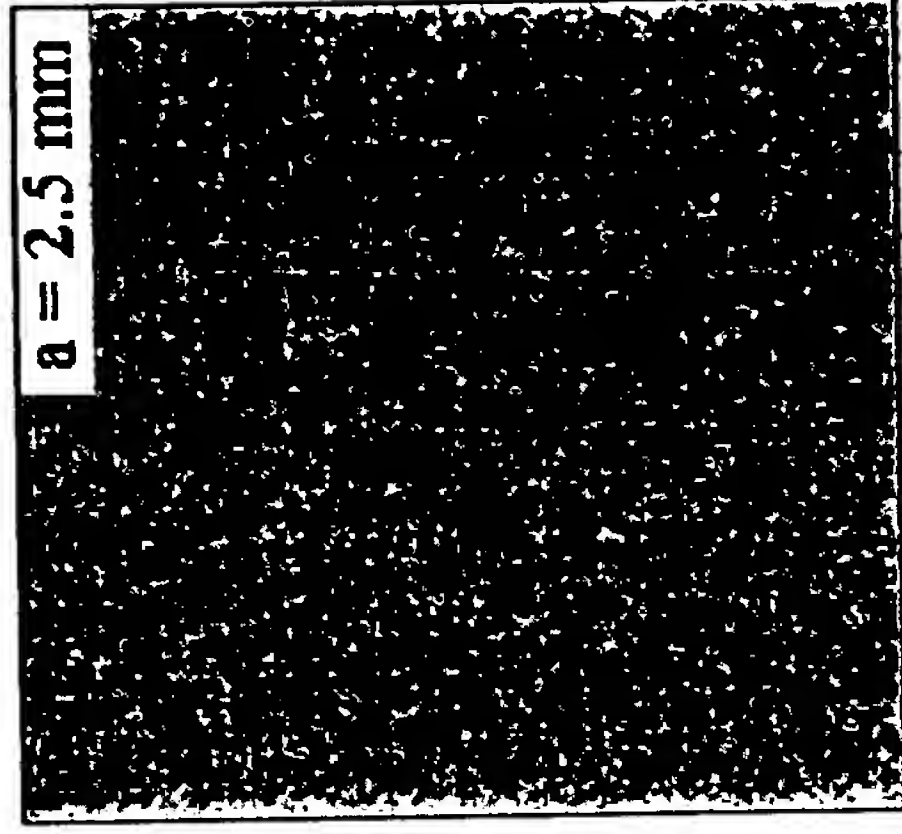


Figure 32B

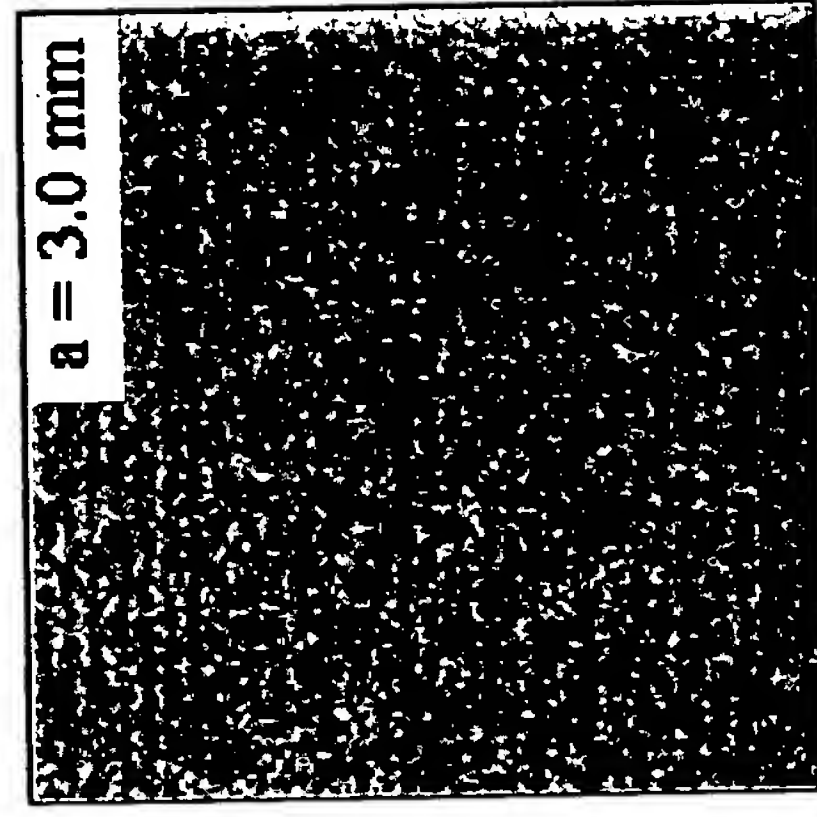


Figure 32C

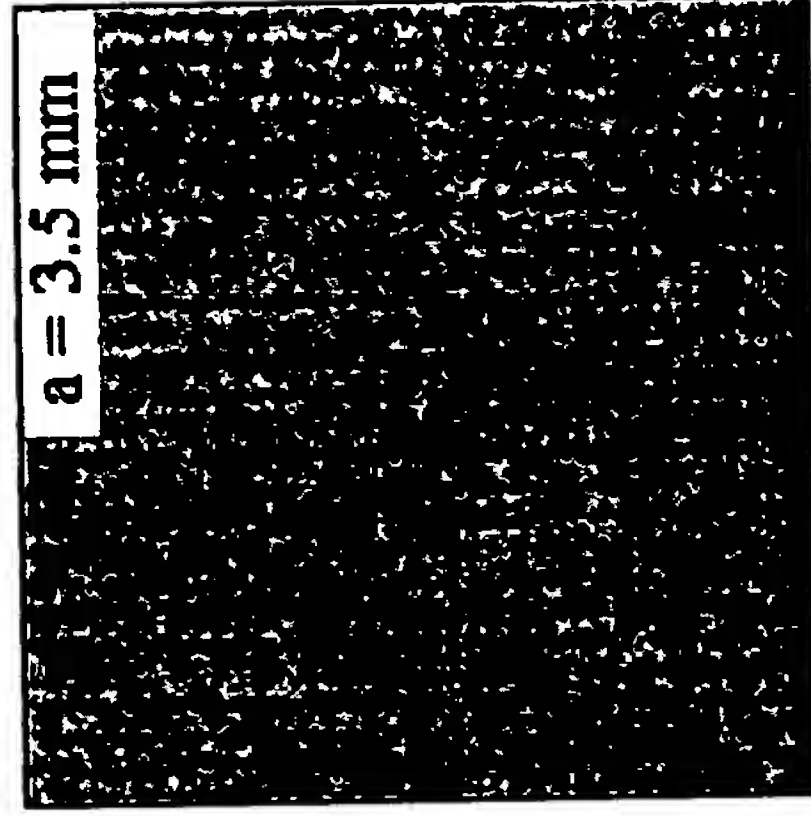


Figure 32D

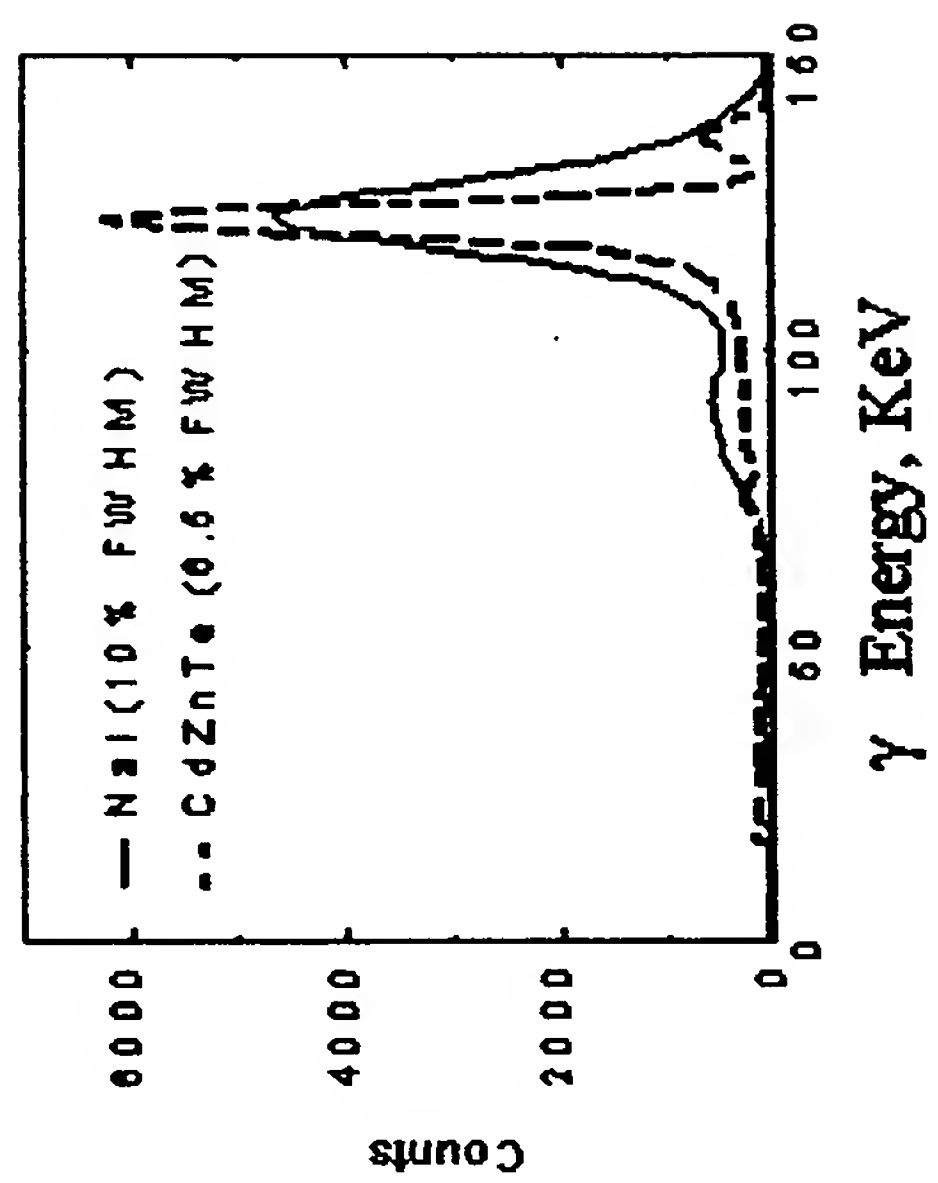
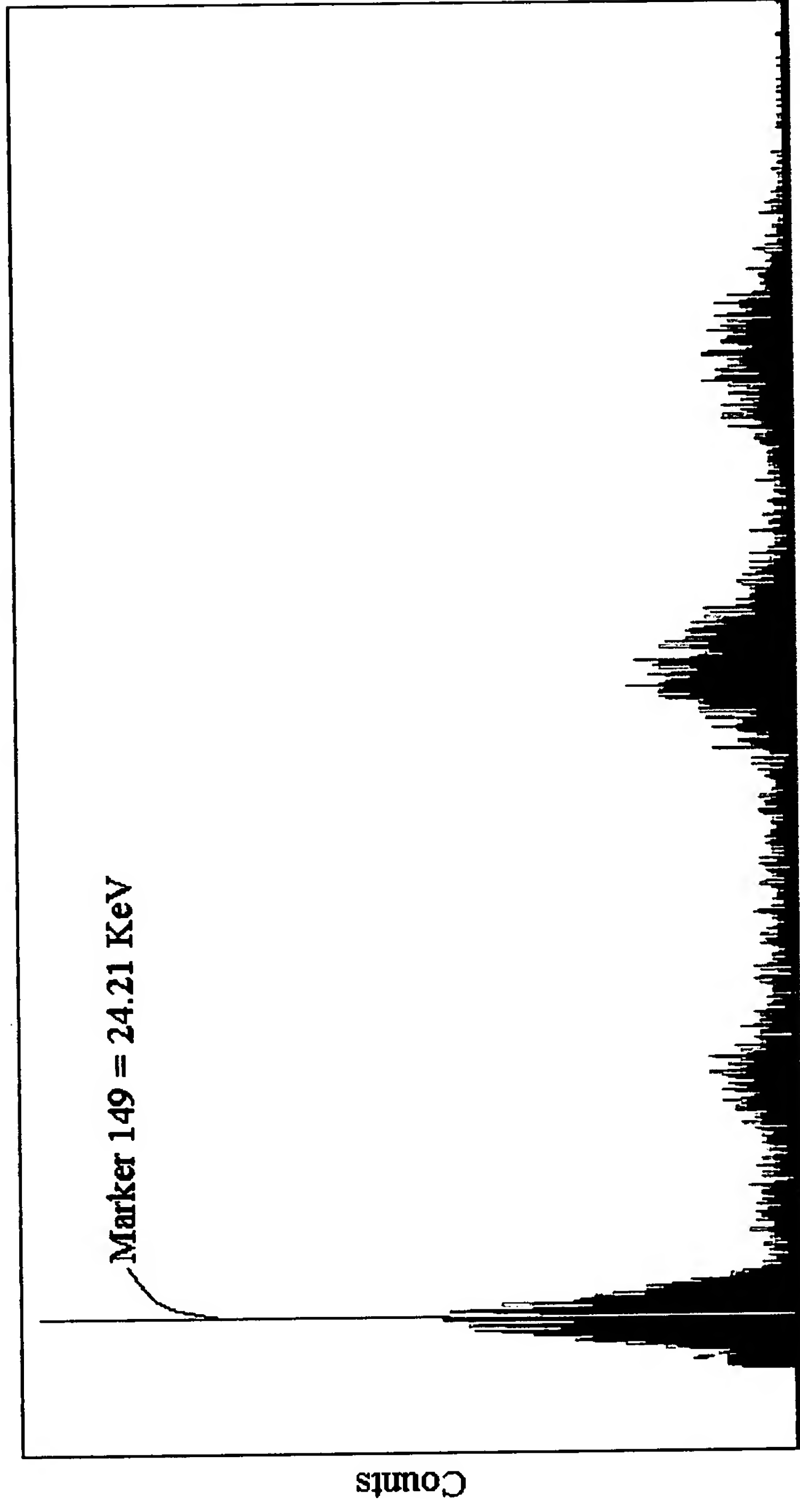


Figure 33A



Energy

Figure 33B

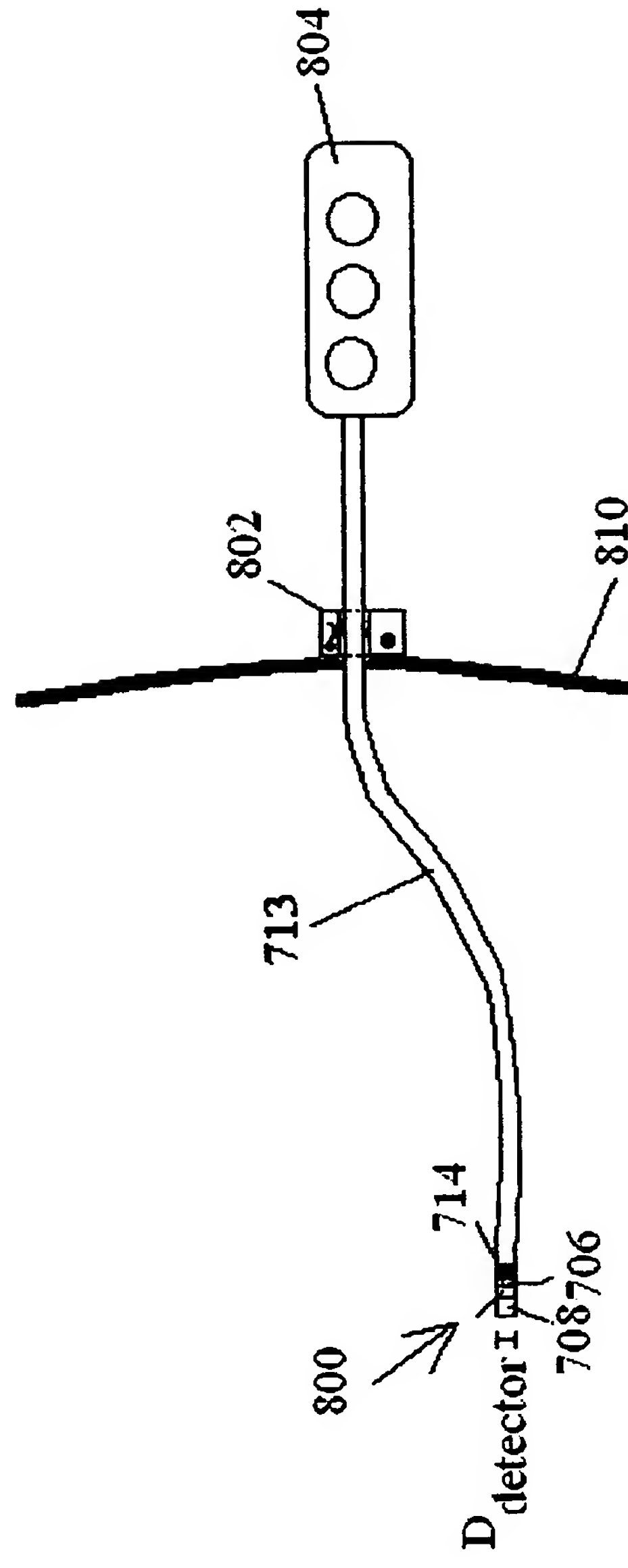


Figure 34A

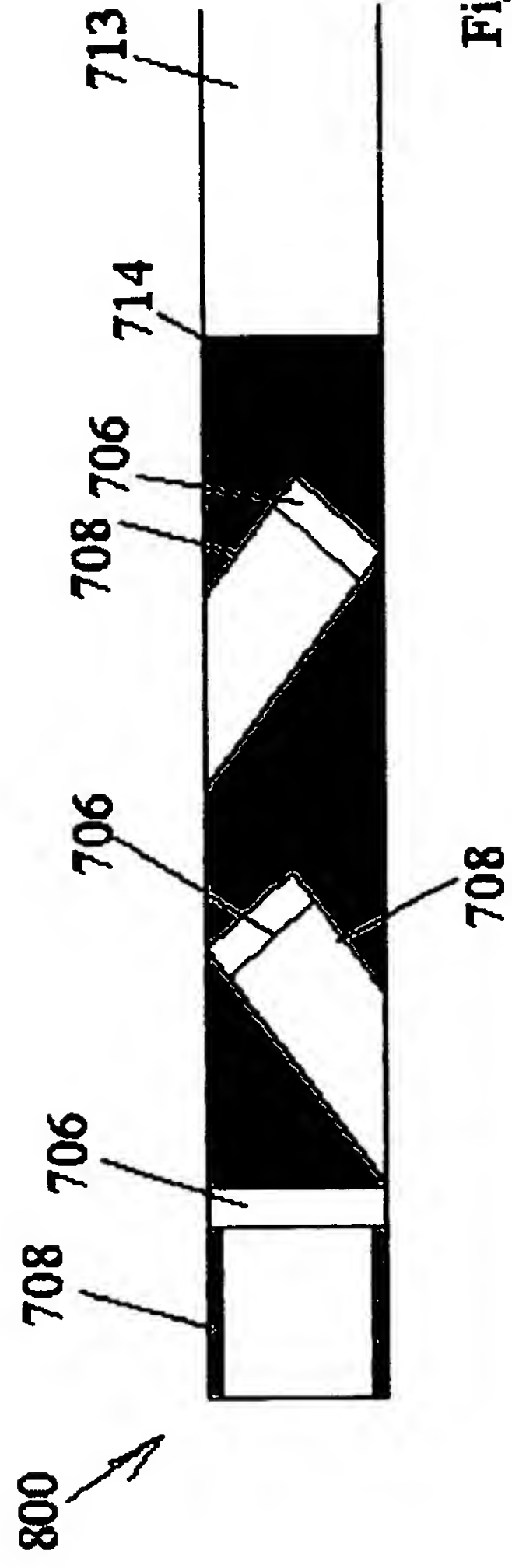


Figure 34B

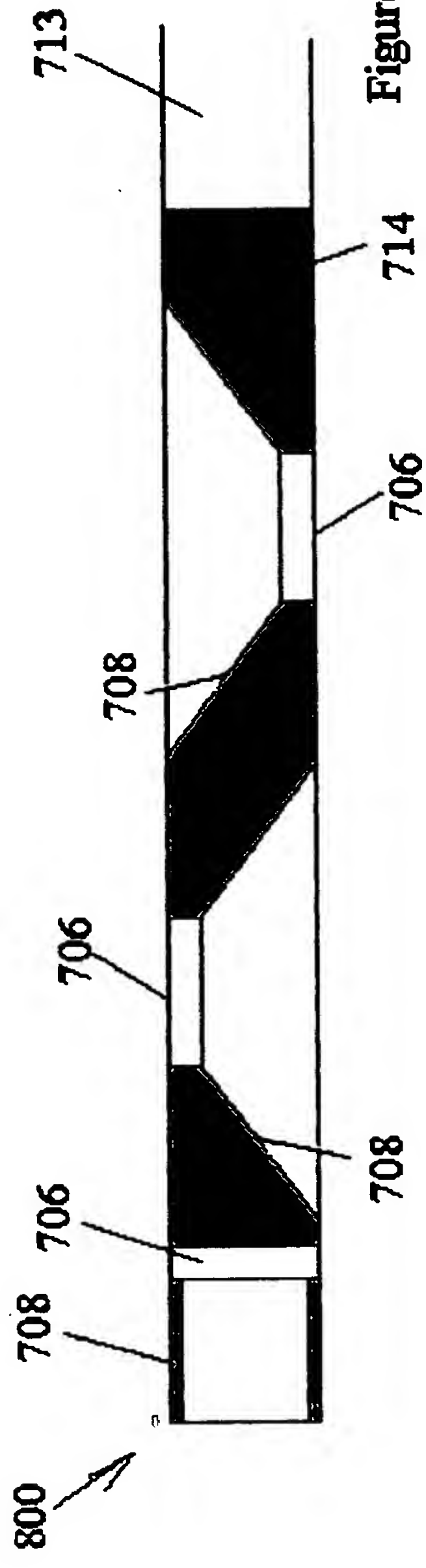


Figure 34C



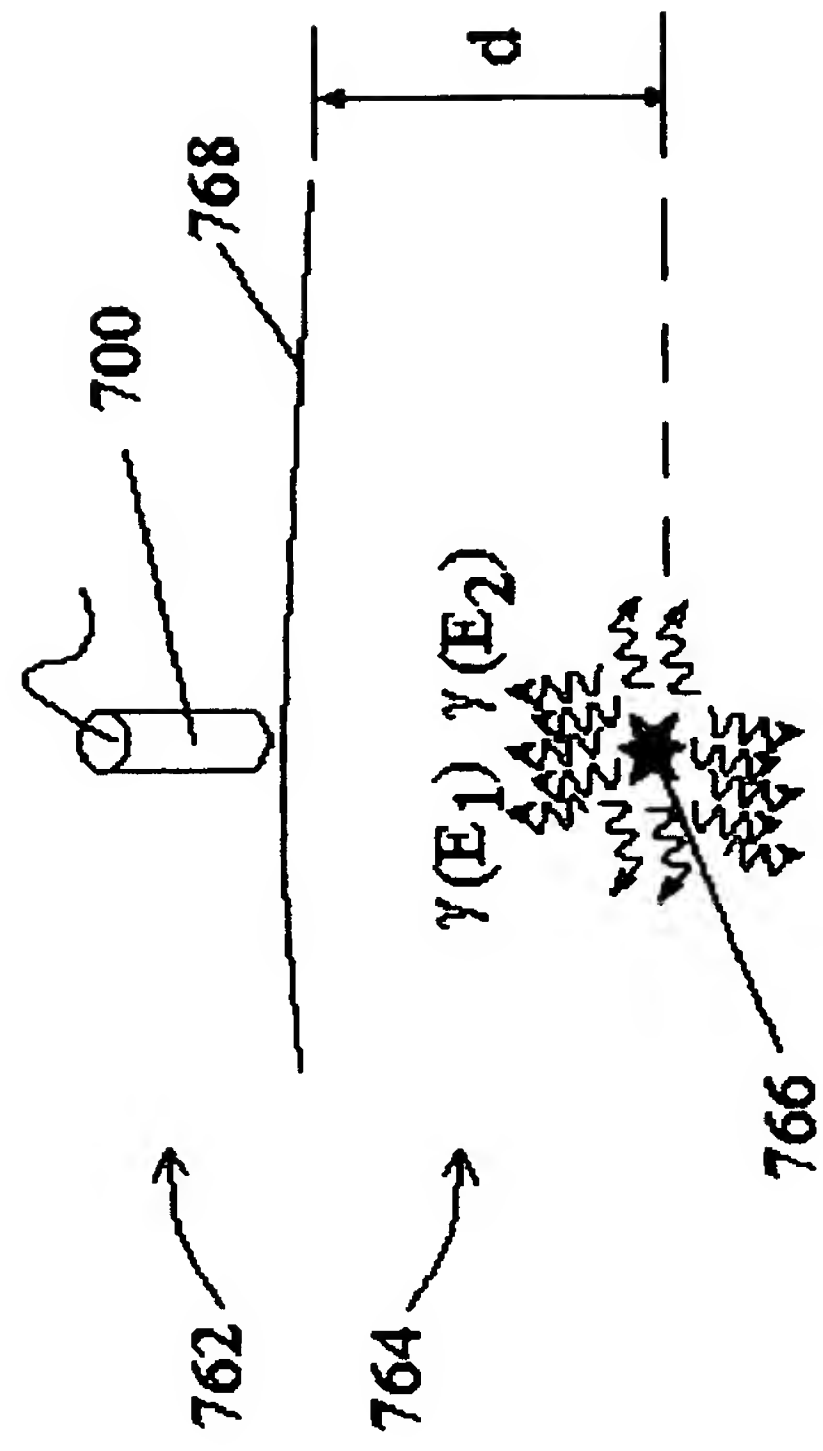


Figure 35

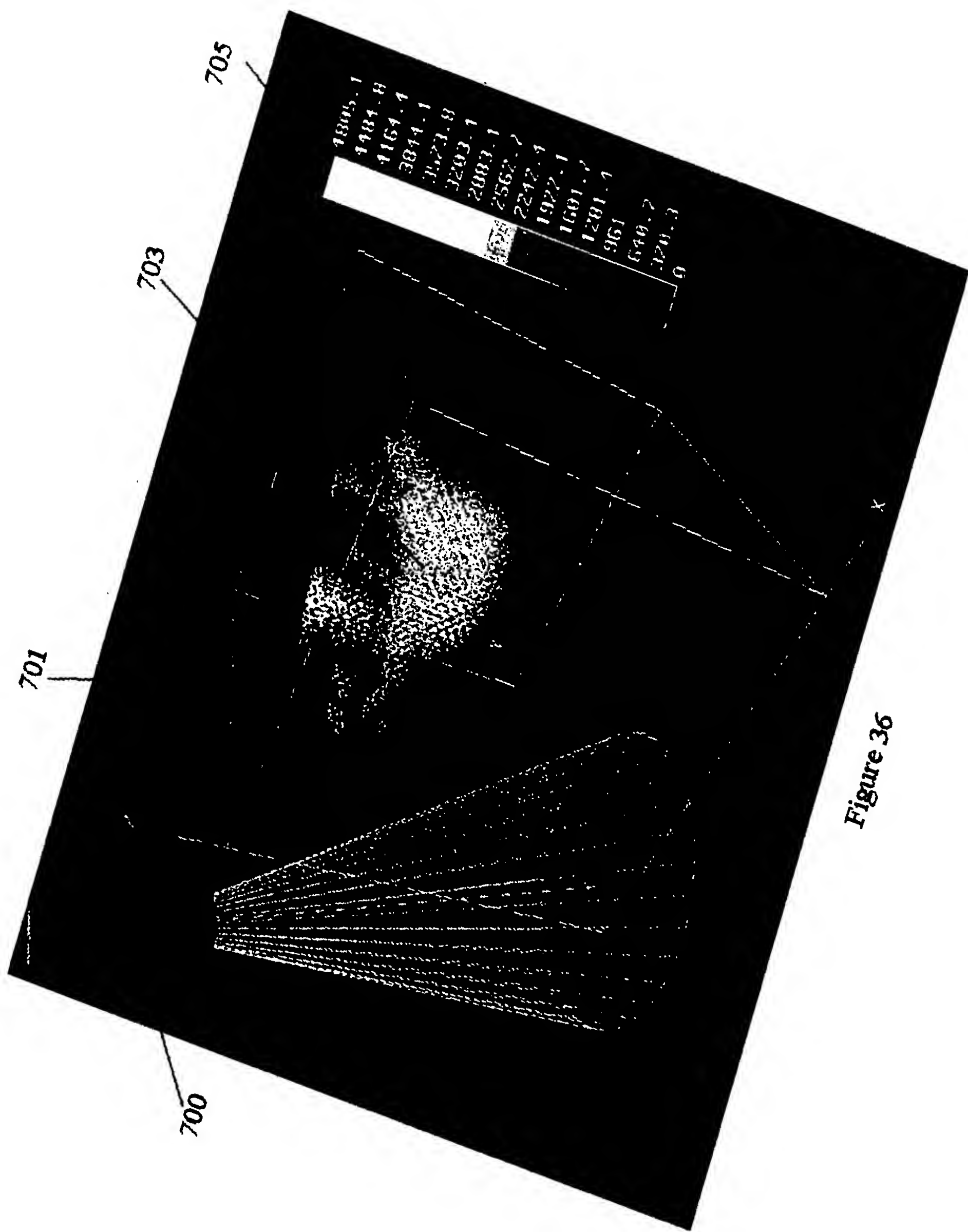


Figure 36